

# **NX-414: Brain-like computation and intelligence**

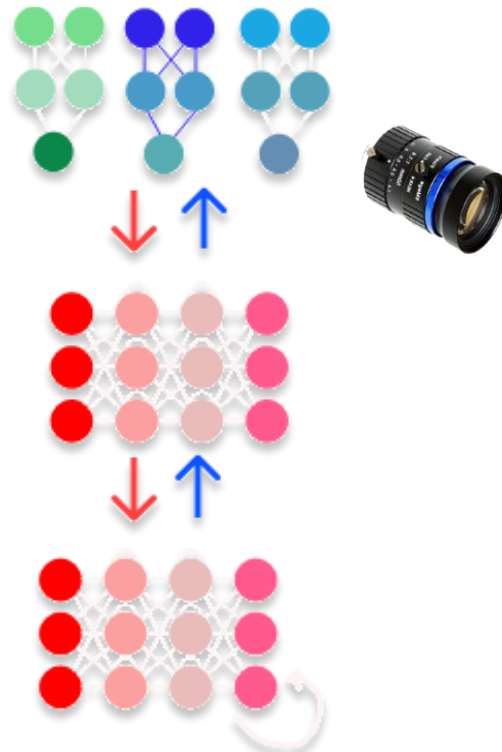
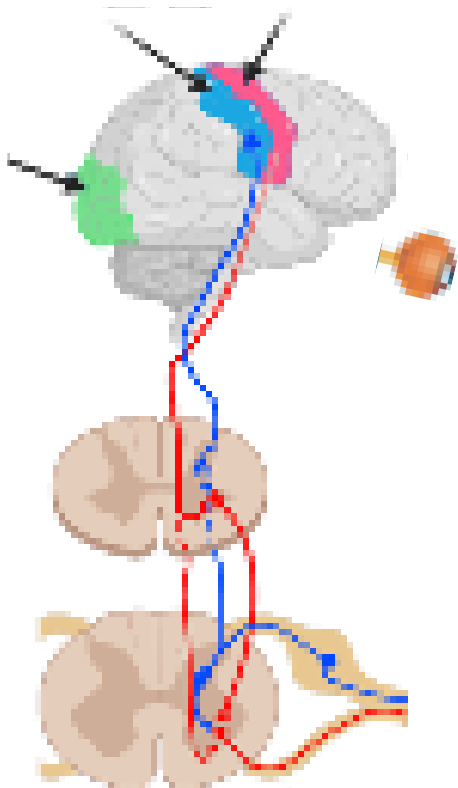
Martin Schrimpf

Lecture 6, March 26 2025

Biological Intelligence



Artificial Intelligence



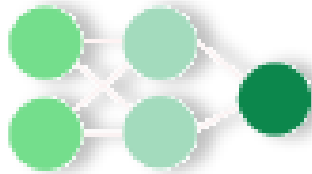
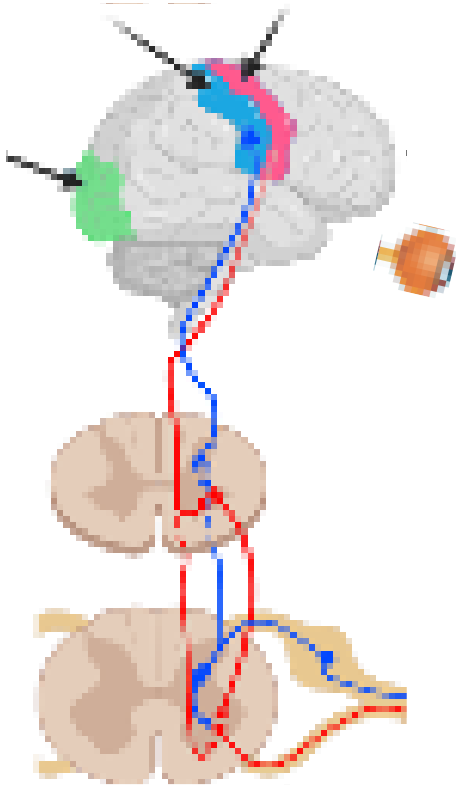
# Normative frameworks

## Information theoretic

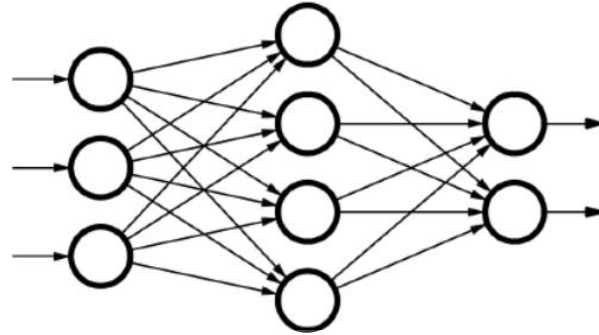
e.g. sparse coding,  
redundancy reduction,  
mutual information ...

## Utilitarian

e.g. **recognize objects**,  
chase prey, navigate ...



# Using deep neural networks as goal-driven models of a system



Vision: object recognition.

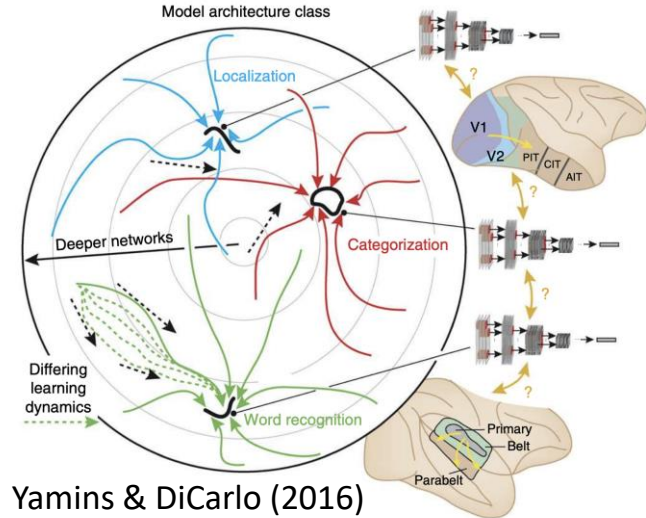
Yamins & Hong et al. (2014), Schrimpf & Kubilius et al. (2018)



Audition: speech recognition, speaker & sound identification. Kell et al. (2018)



Somatosensation: shape recognition. Zhuang et al. (2017)



Language: next-word prediction.

Schrimpf et al. (2021)

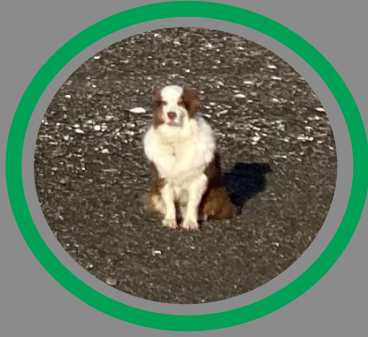


Decision making: context-dependent choice. Mante & Sussilo et al. (2013)

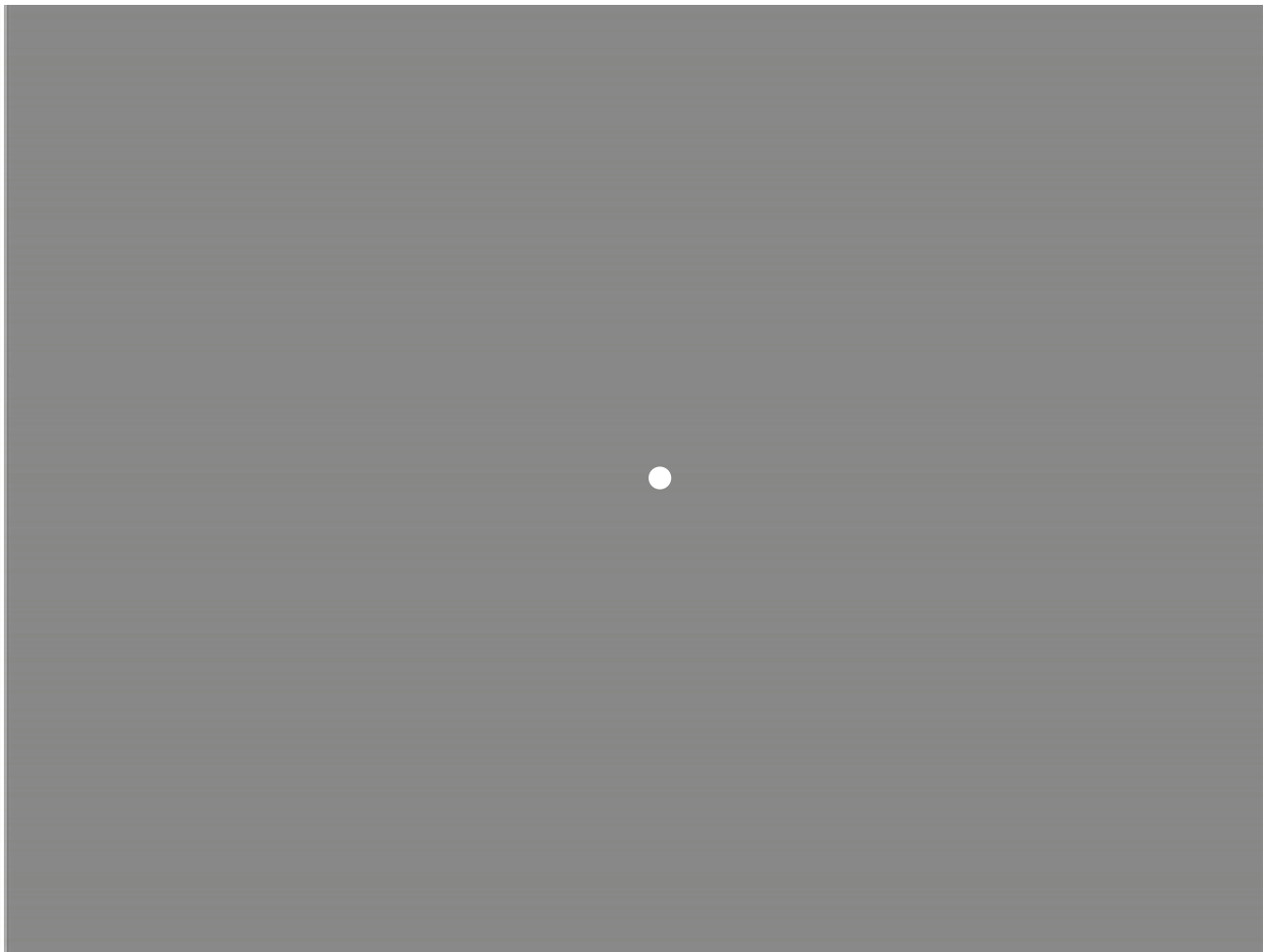


Proprioception: action recognition. Sandbrink et al. (2023)

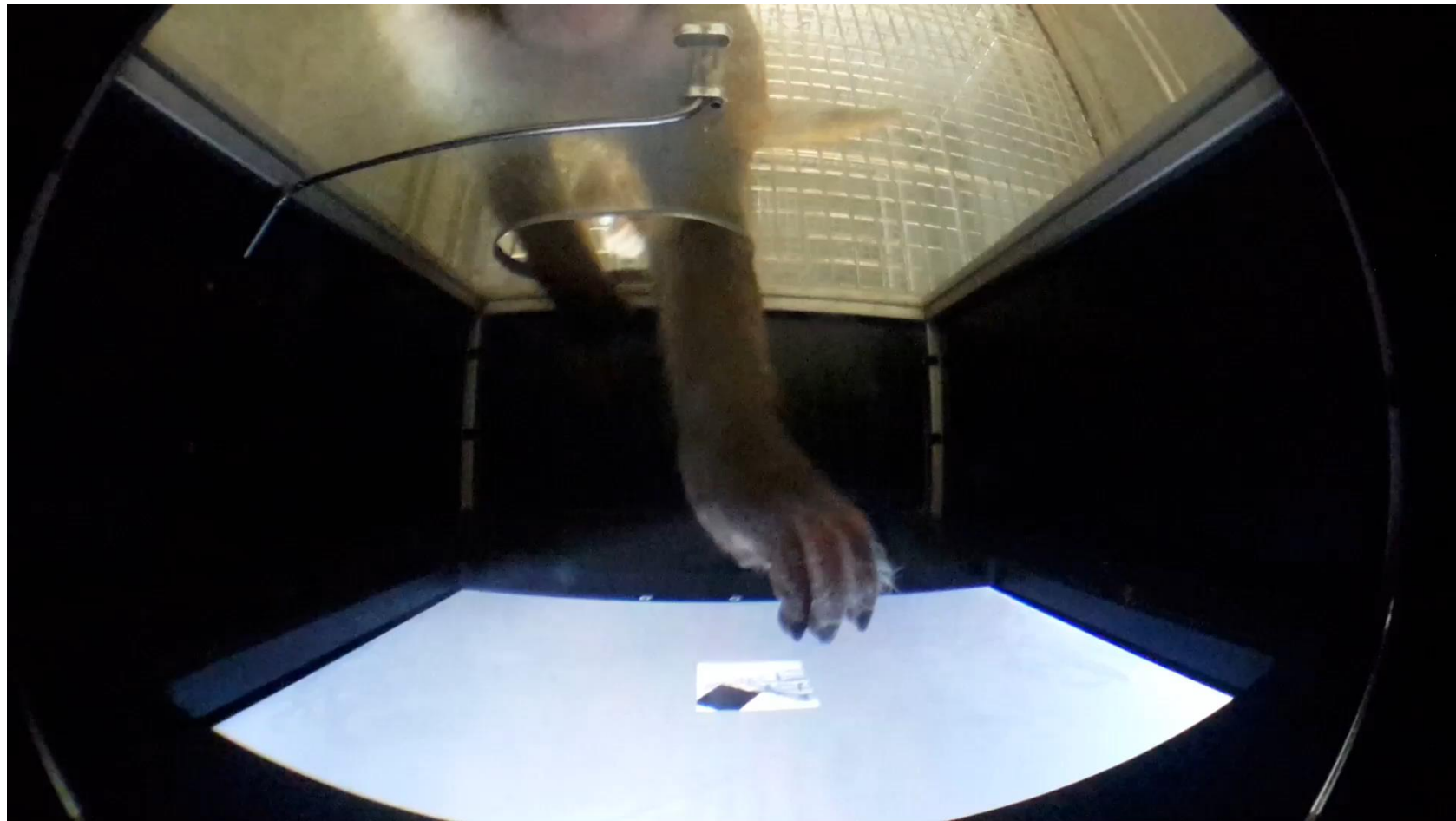
# Behavioral experiment



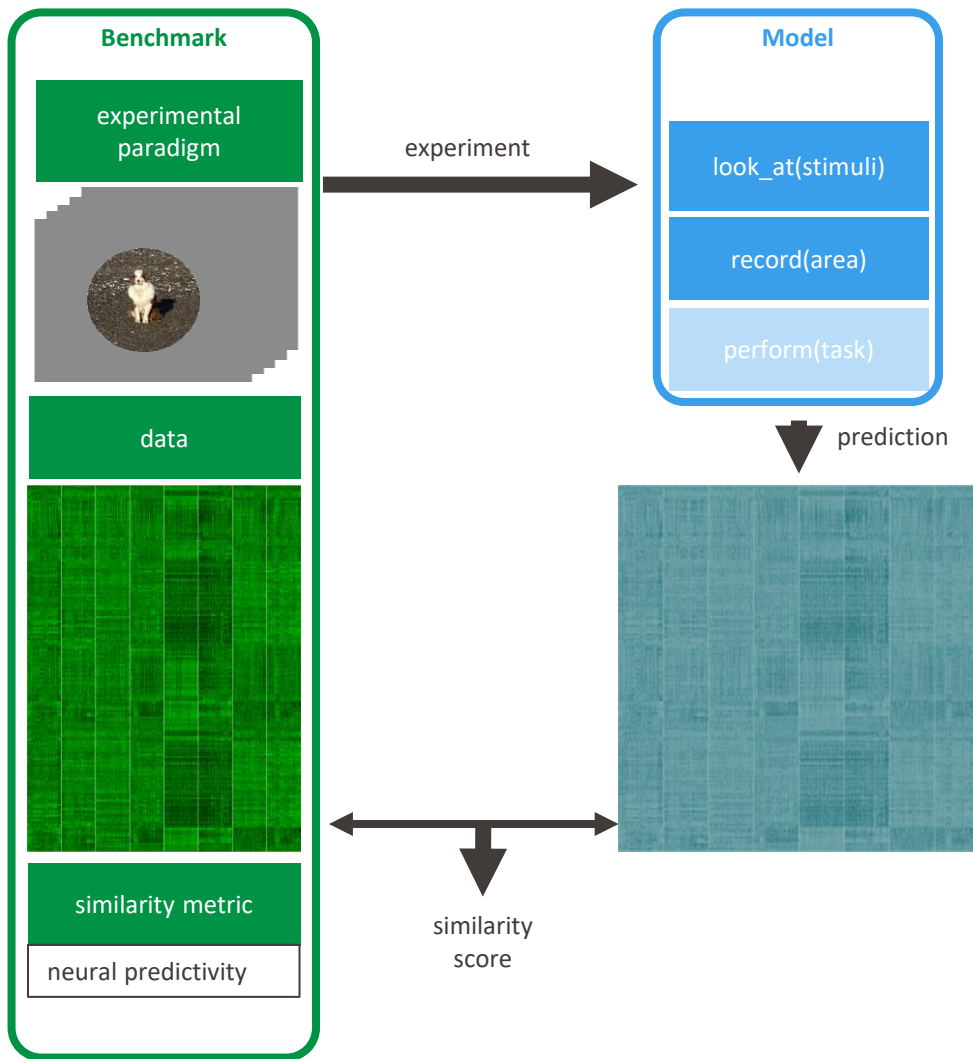
# Behavioral experiment



# Neural data

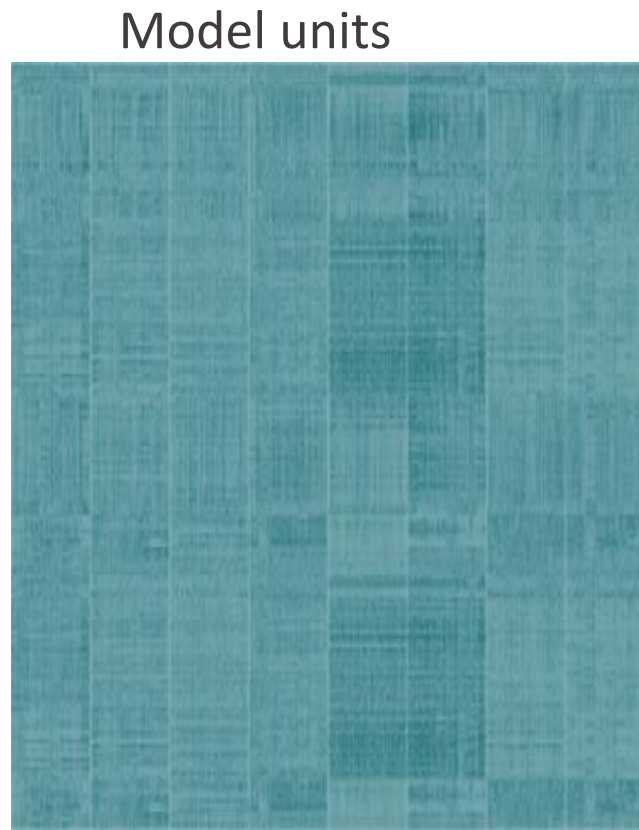
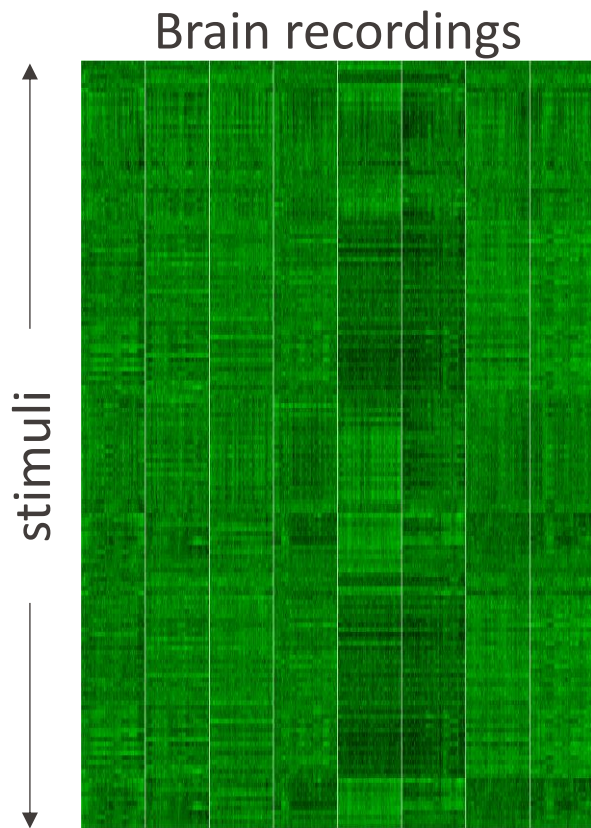


# Neural benchmark



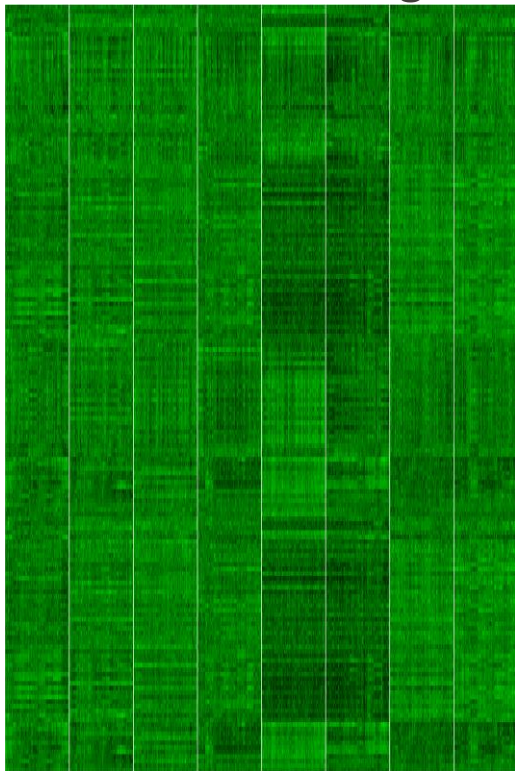
Neural alignment = alignment between  
stimulus-matched recordings

# Neural benchmarks



# Neural benchmarks

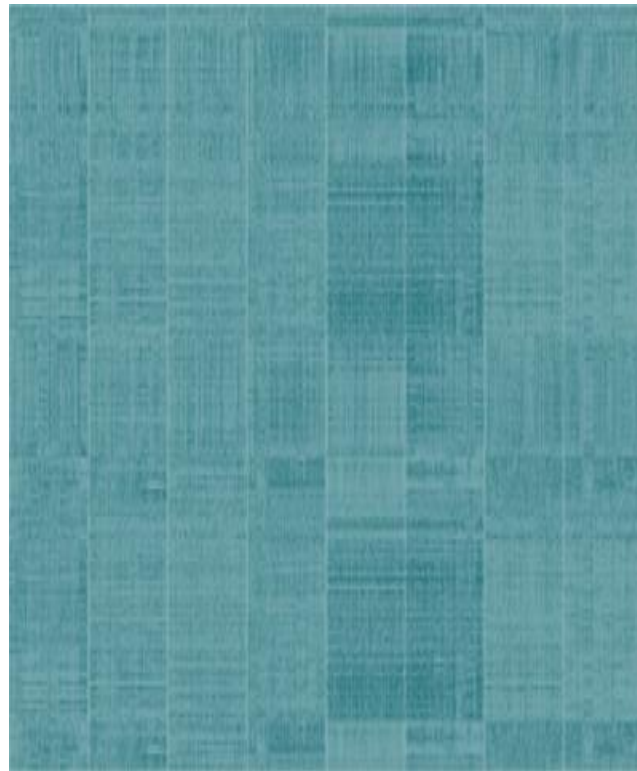
stimuli



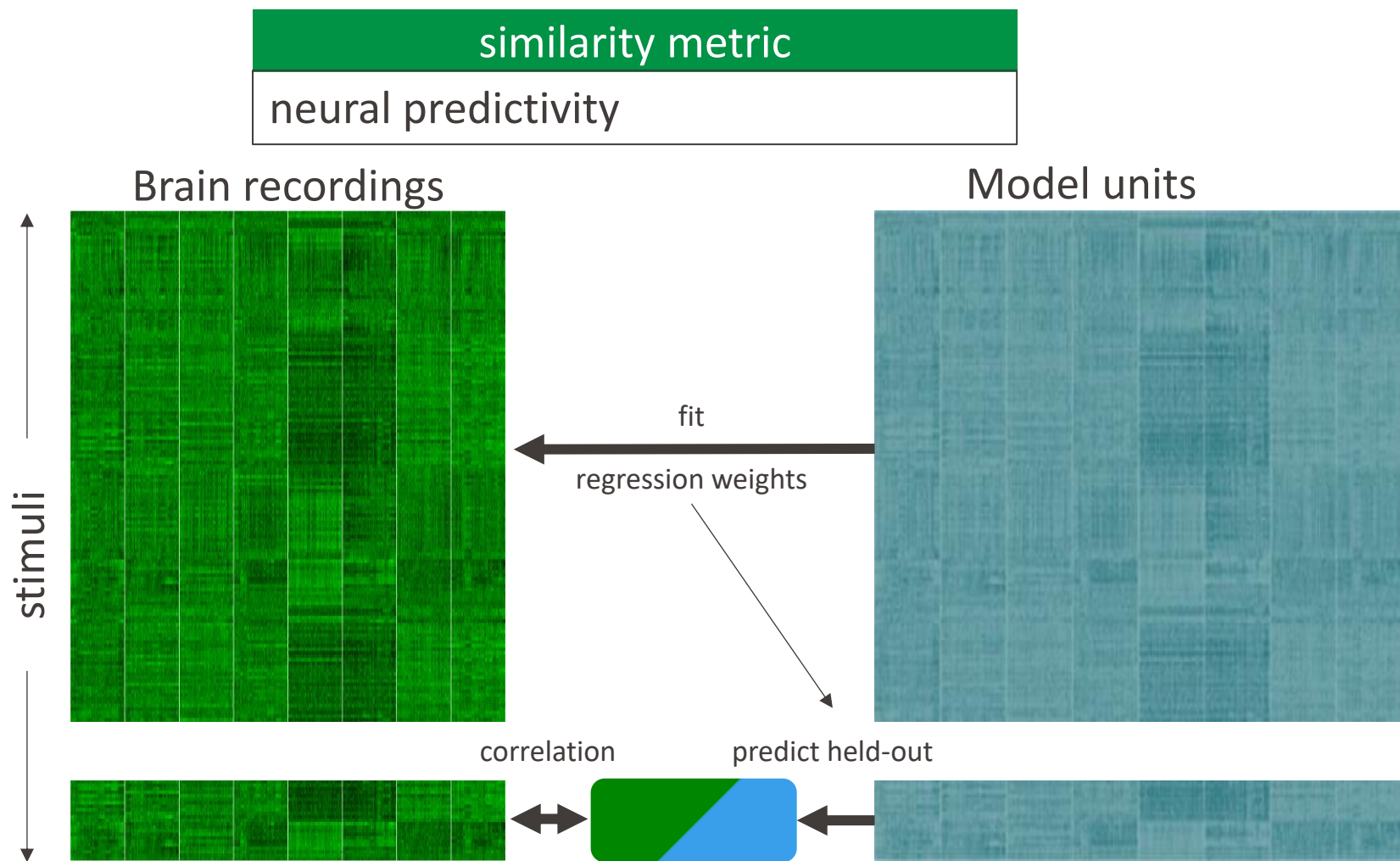
similarity metric

neural predictivity

Model units

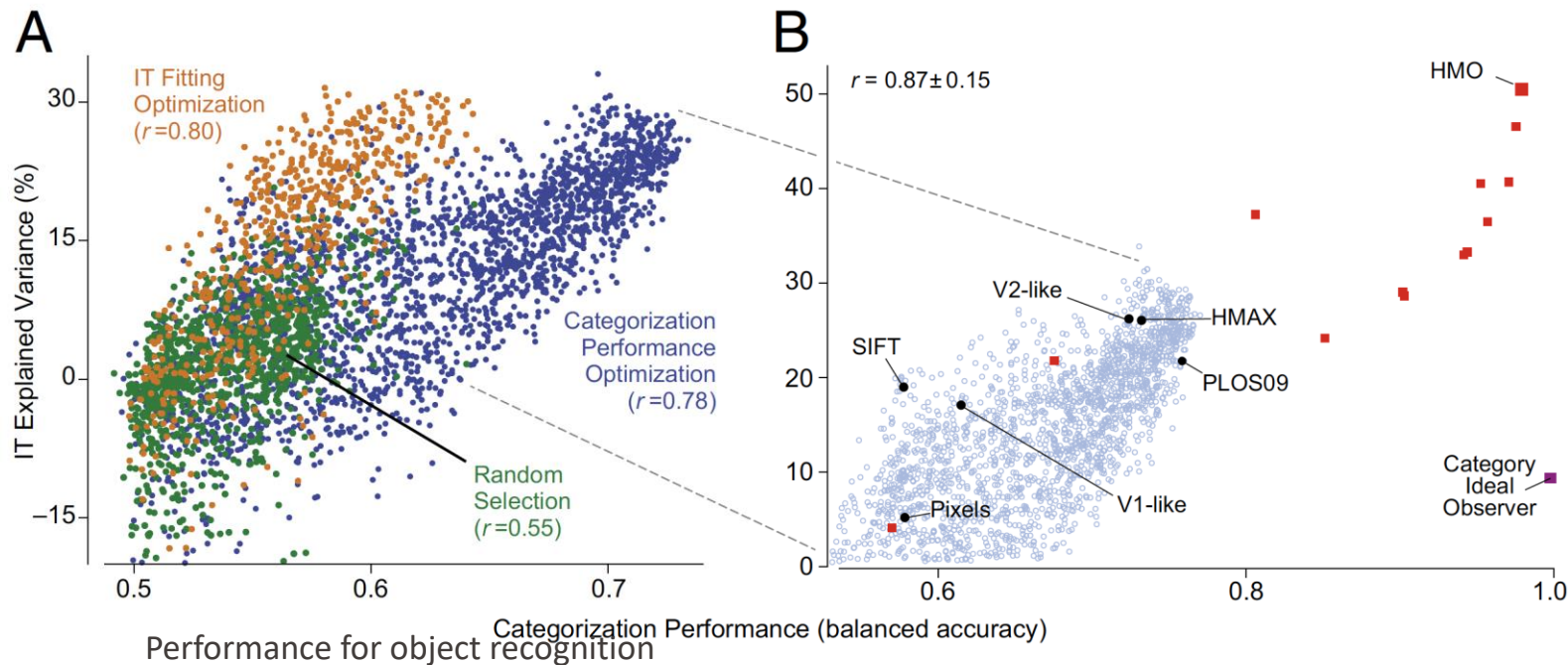


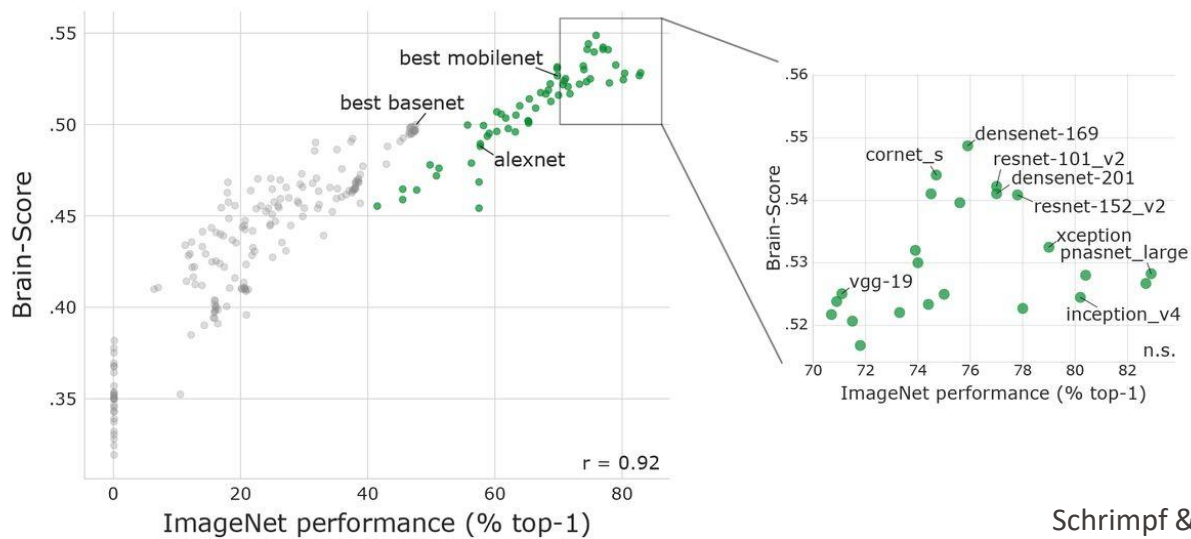
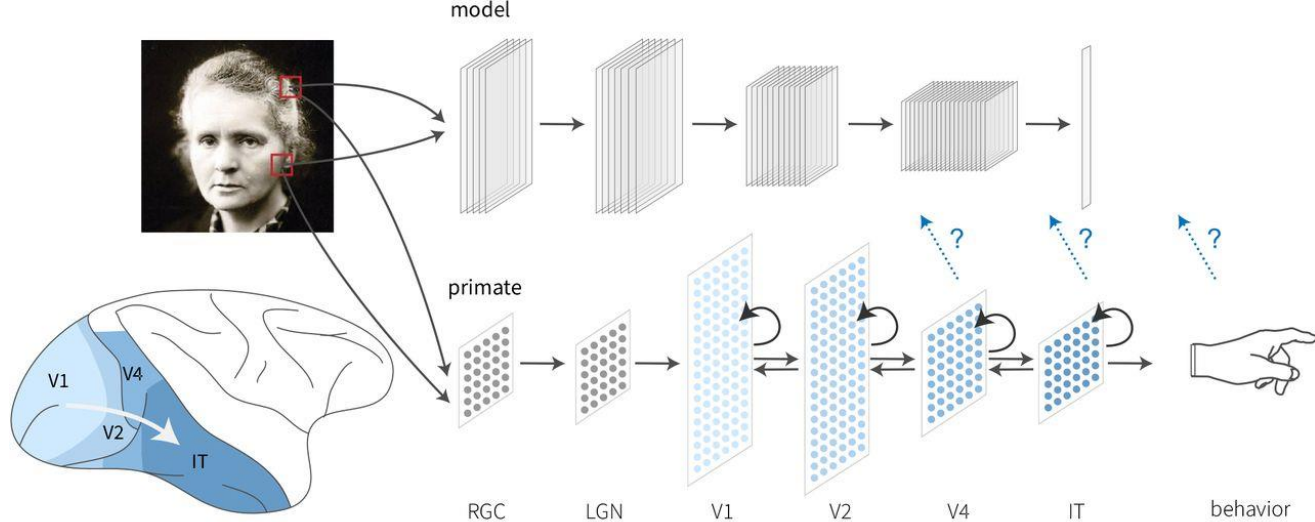
## Neural benchmarks





# Large scale architecture search and model comparison



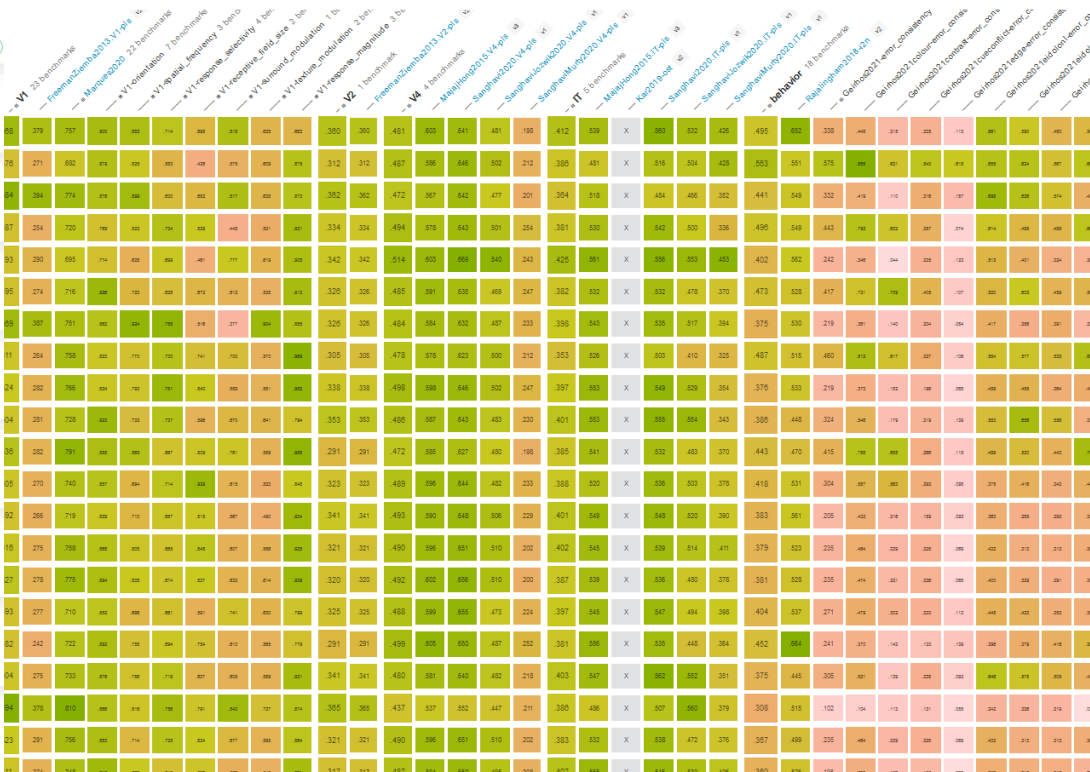


# Brain-Score 100+ brain & behavior benchmarks, 300+ models

e.g. neural predictions for different image sets, distributional alignments such as spatial frequency, behavioral generalization, ...

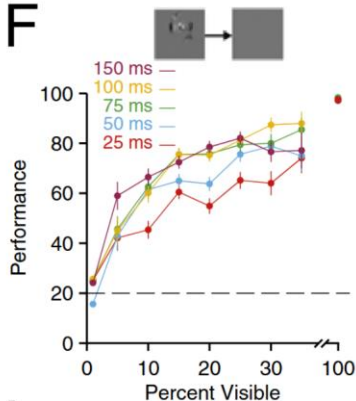
[www.Brain-Score.org](http://www.Brain-Score.org)

Rank	Model	average 81	neural 38	behavior 43
1	convnext_large_mlp:clip_laio	.467	.378	.555
2	convnext_xlarge:fb_in22k_ft	.449	.338	.560
3	vit_base_patch16_clip_224:o	.445	.343	.548
4	vit_large_patch14_clip_224:la	.445	.332	.559
5	vit_large_patch14_clip_224:o	.443	.341	.545
6	vit_base_patch16_clip_224:o	.442	.352	.532
7	vit_repos_base_patch16_cls	.437	.381	.494
8	cvt_cvt-w24-384-in22k_finetuned-in1k_4	.430	.327	.533

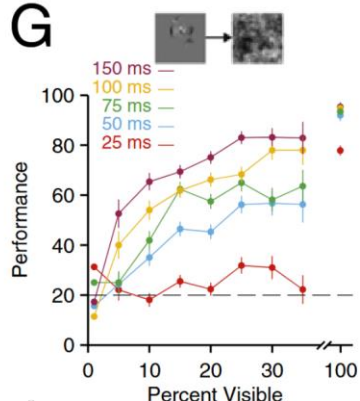


# Recurrent processing in the visual system

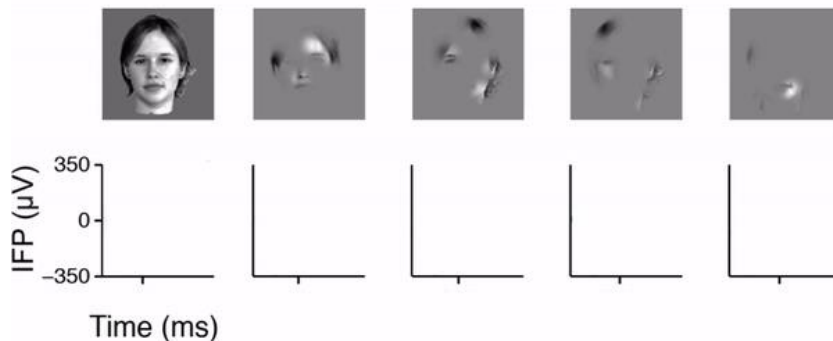
F



G

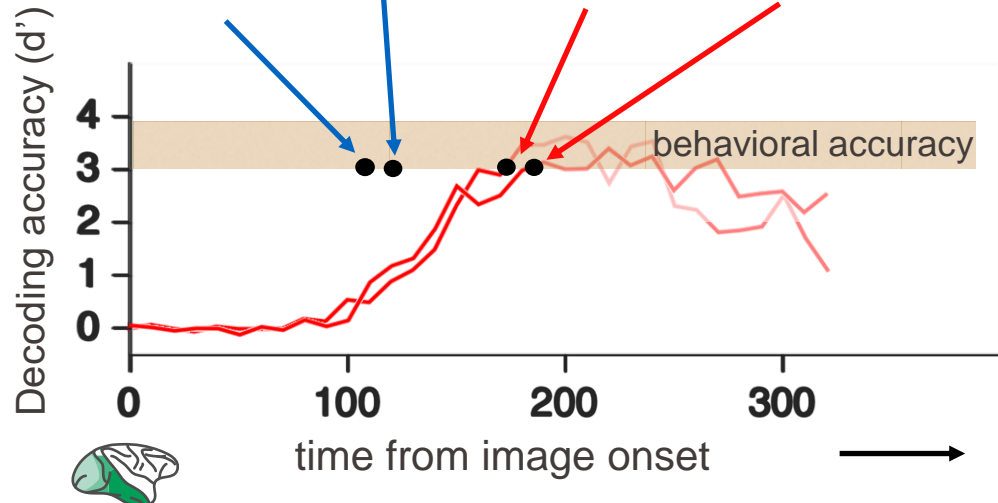
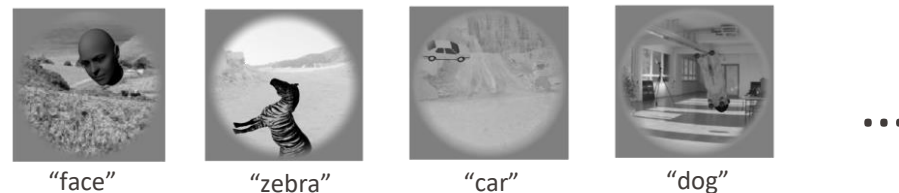


Electrode in left fusiform gyrus (face-selective)



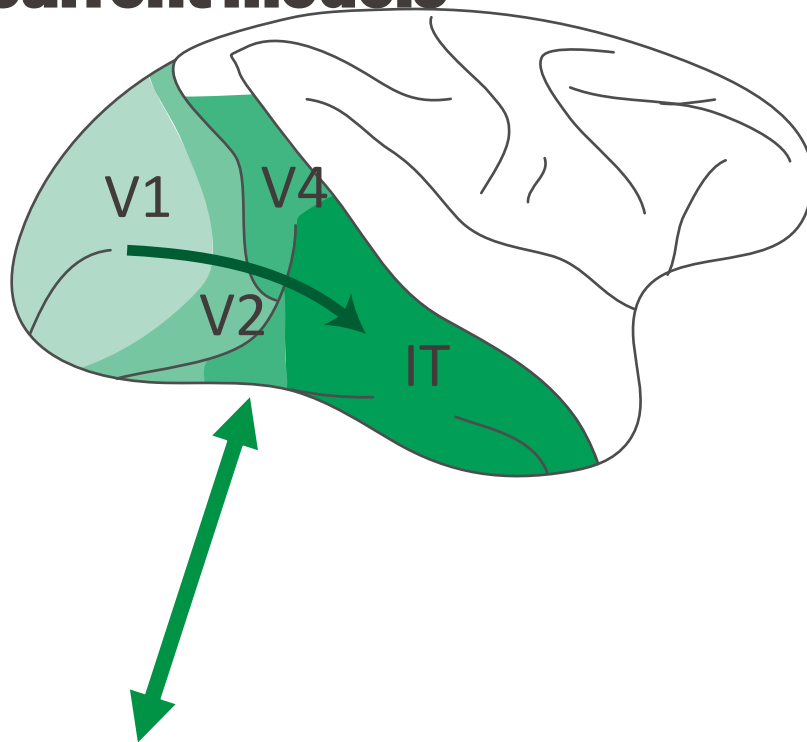
Tang & Schrimpf & Lotter et al. 2018

- Control images are solved quickly
- Challenge images require more processing



Kar et al. 2019

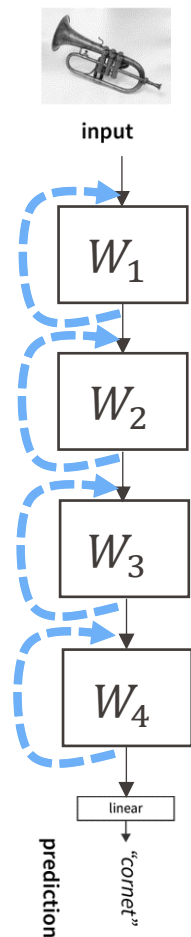
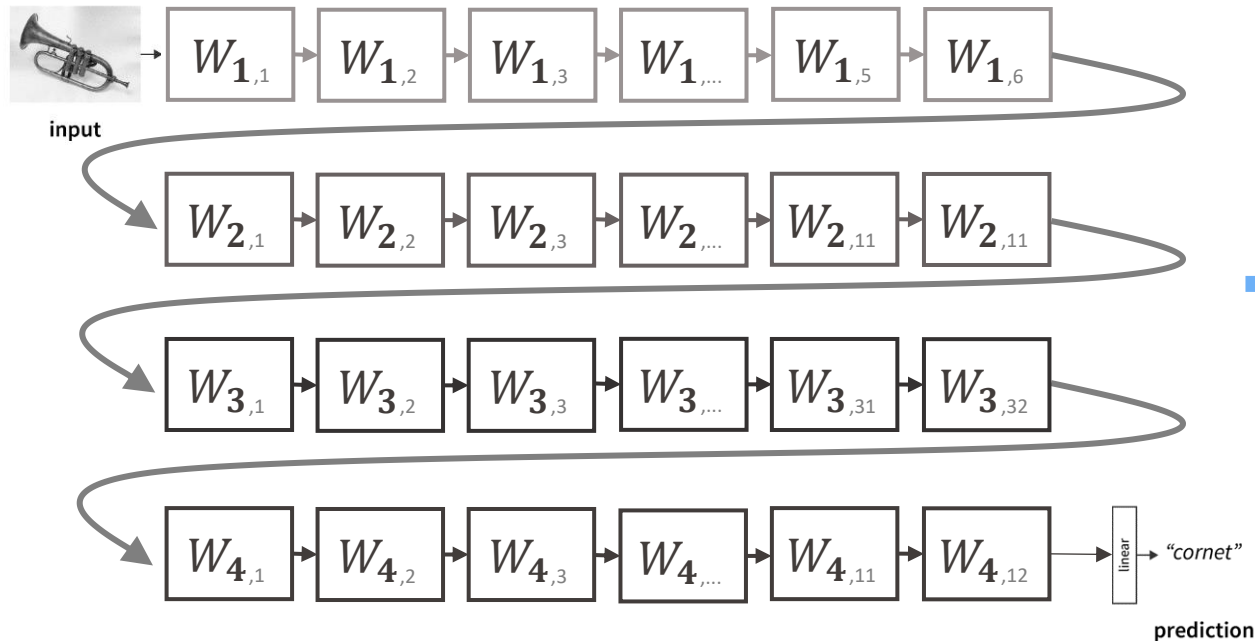
# Modeling recurrence: transform feed-forward networks into recurrent models



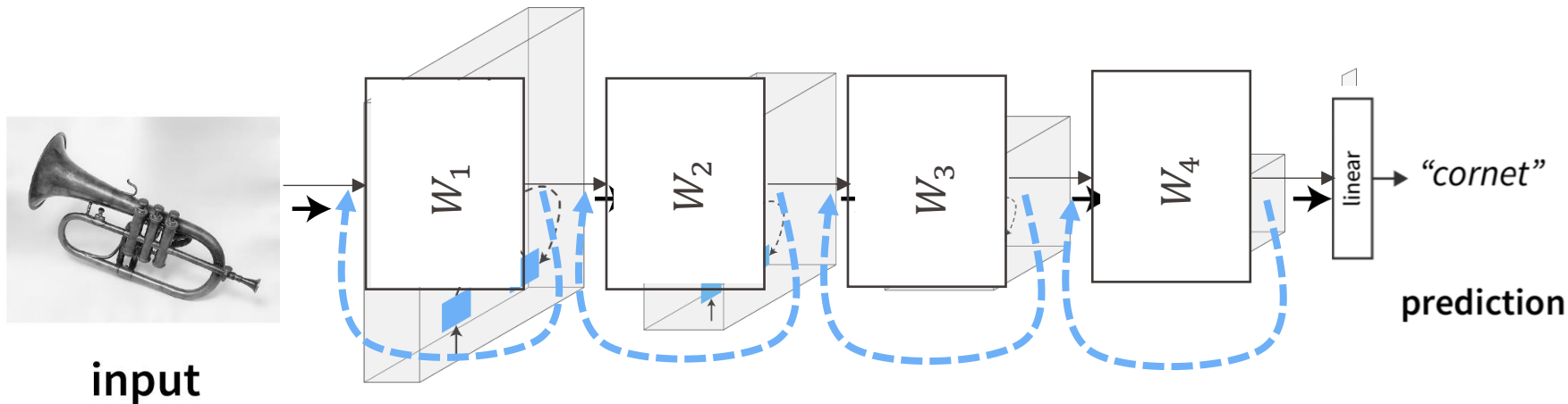
e.g. ResNet-101



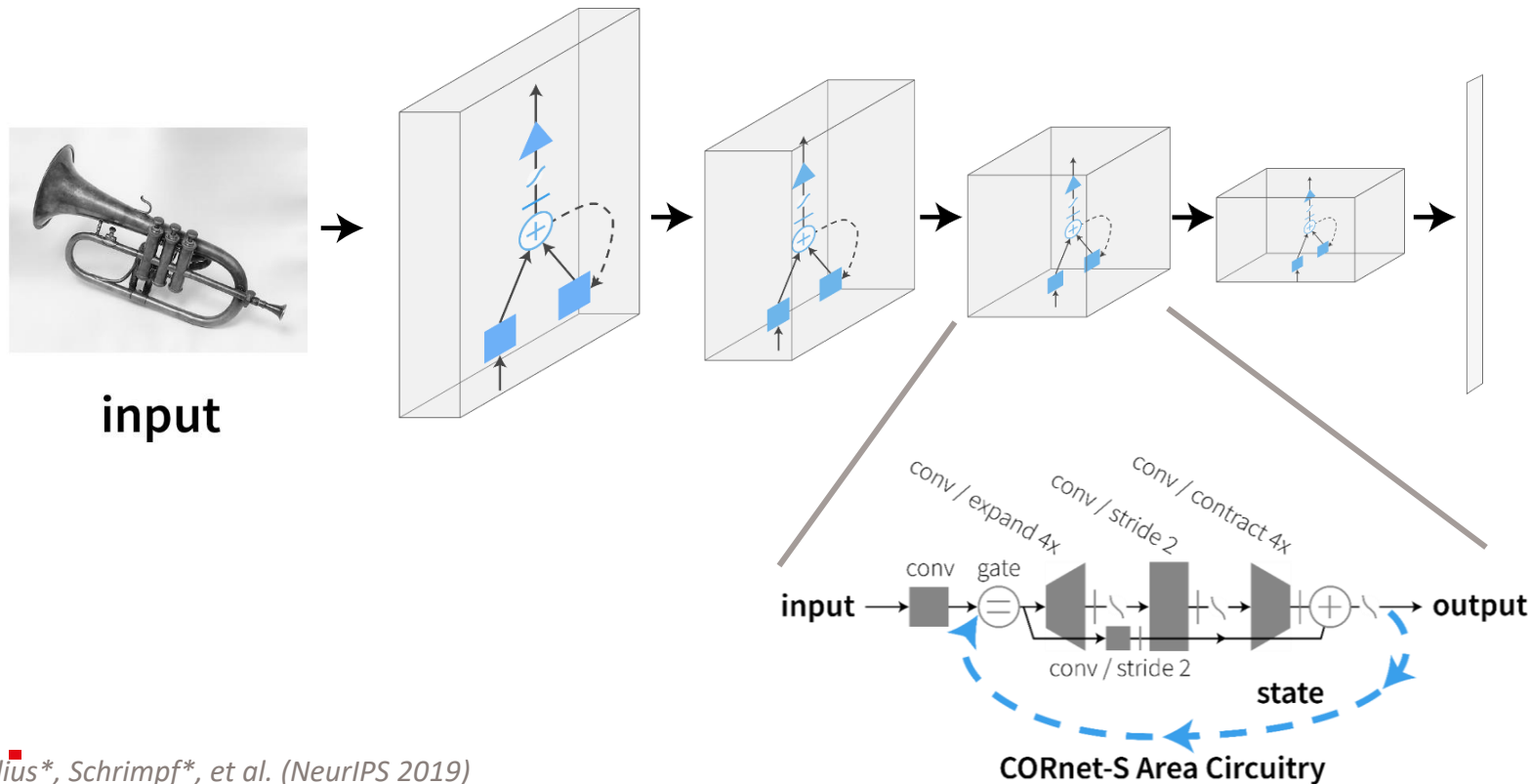
# Transform feed-forward networks into recurrent models



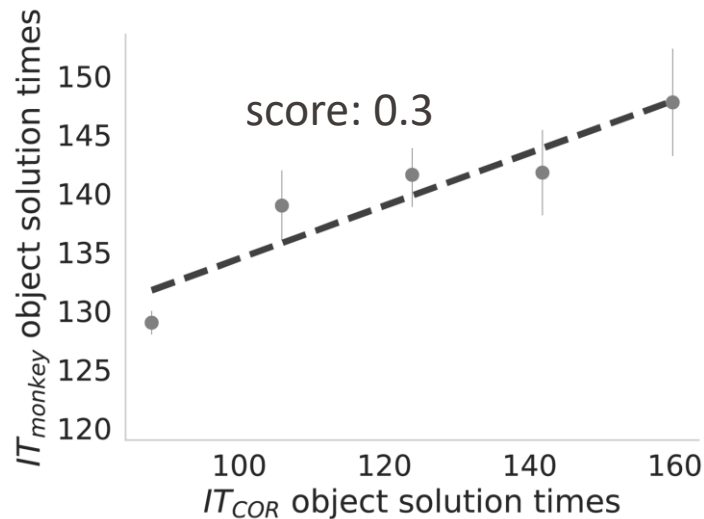
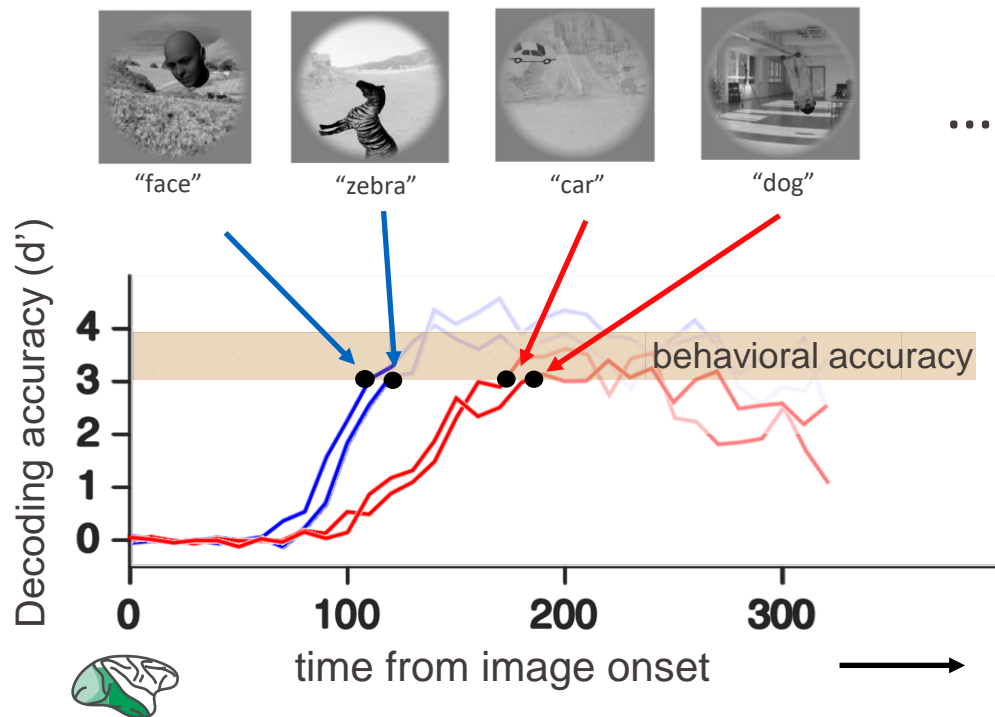
# Modeling recurrence: transform feed-forward networks into recurrent models: CORnet



# Recurrent CORnet model: compact architecture via recurrence



# Recurrent model predicts temporal dynamics in IT



- Unlike feedforward models, CORnet-S can **predict neural responses over time**.
- i.e., when the **brain's IT is fast** to process images, **CORnet's IT-layer is also fast**

# EPFL Unsupervised learning with a contrastive loss

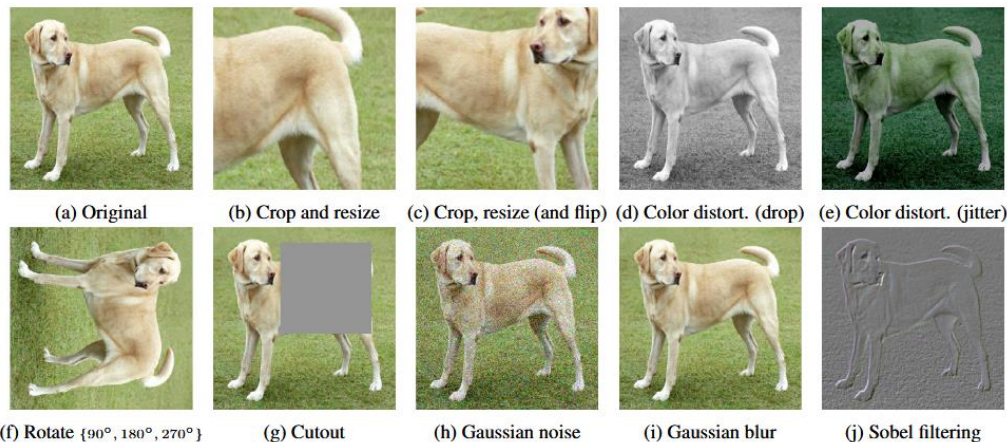
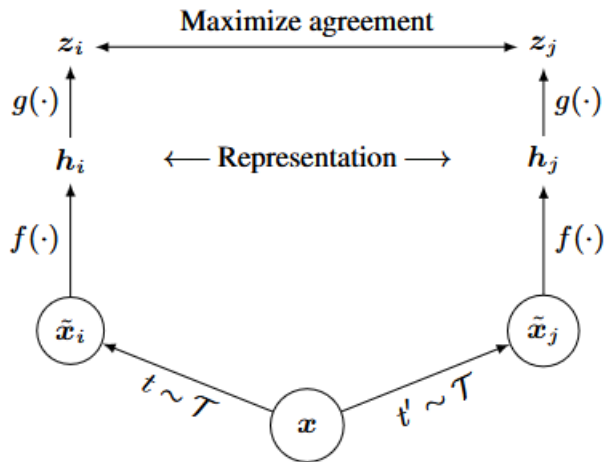
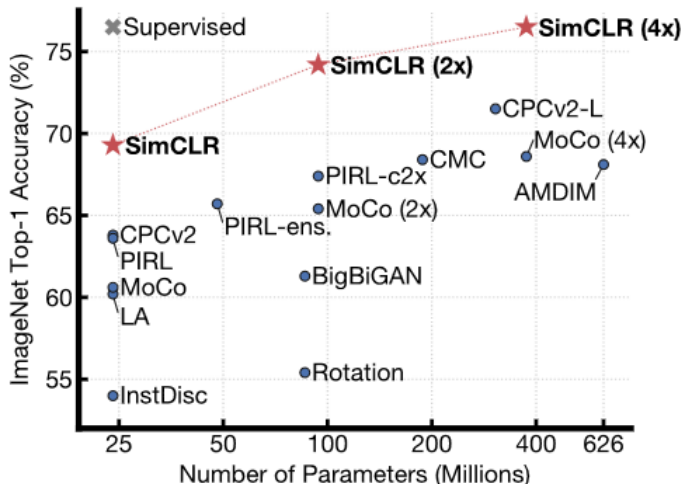
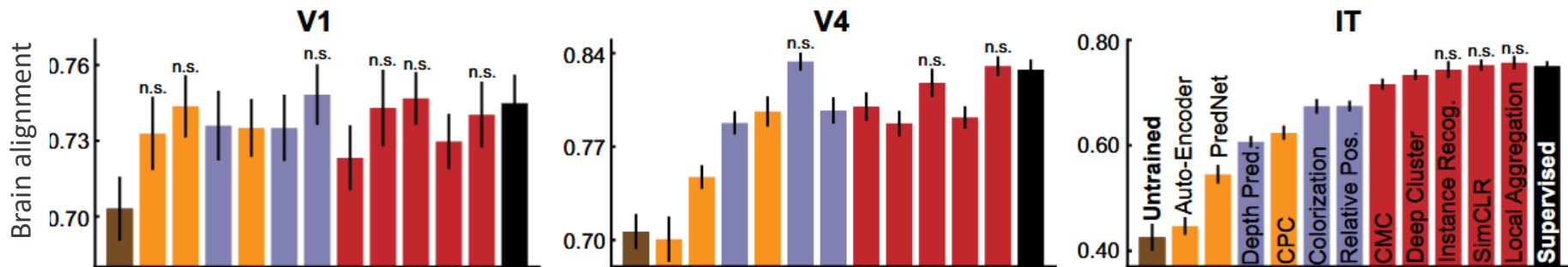


Figure 2. A simple framework for contrastive learning of visual representations. Two separate data augmentation operators are sampled from the same family of augmentations ( $t \sim \mathcal{T}$  and  $t' \sim \mathcal{T}$ ) and applied to each data example to obtain two correlated views. A base encoder network  $f(\cdot)$  and a projection head  $g(\cdot)$  are trained to maximize agreement using a contrastive loss. After training is completed, we throw away the projection head  $g(\cdot)$  and use encoder  $f(\cdot)$  and representation  $h$  for downstream tasks.

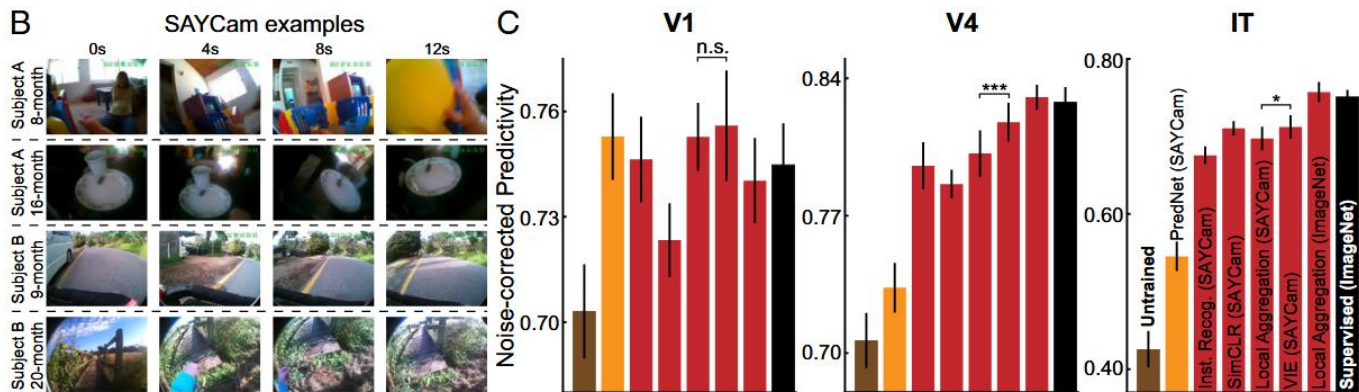


- Unsupervised approaches such as SimCLR encourage similar representations for similar inputs
- Performance rivals supervised learning

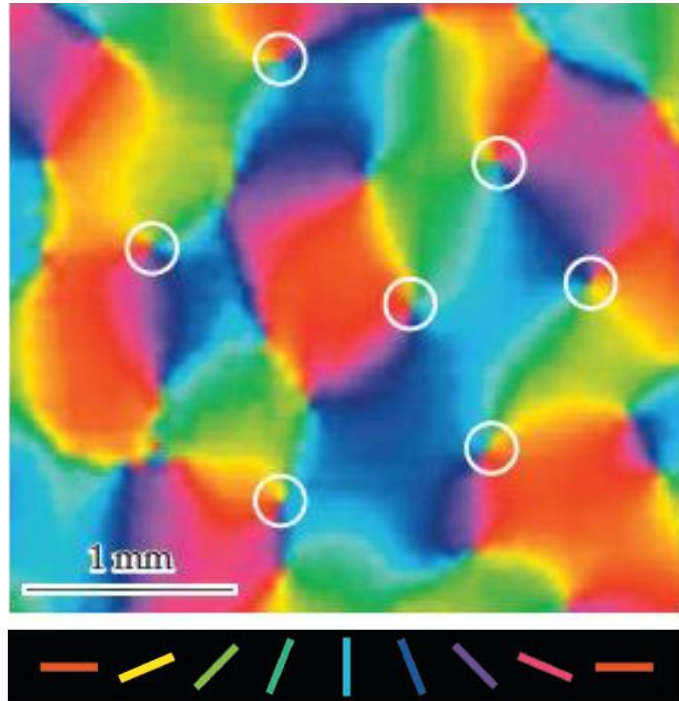
# Unsupervised models also explain visual brain activity



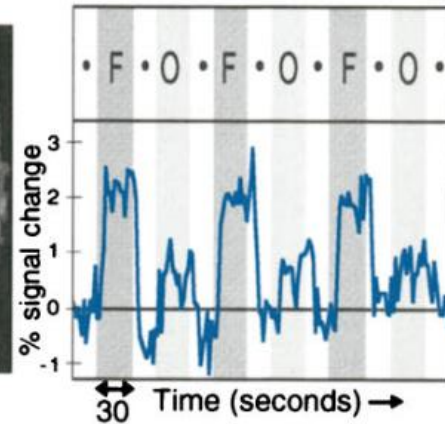
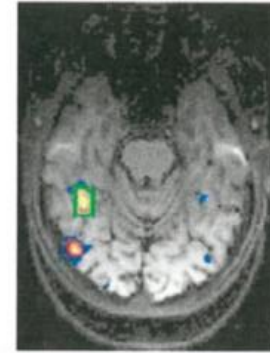
- When trained on regular computer vision datasets (top) or developmental data streams (below, SAYCam), unsupervised models develop brain-like visual representations



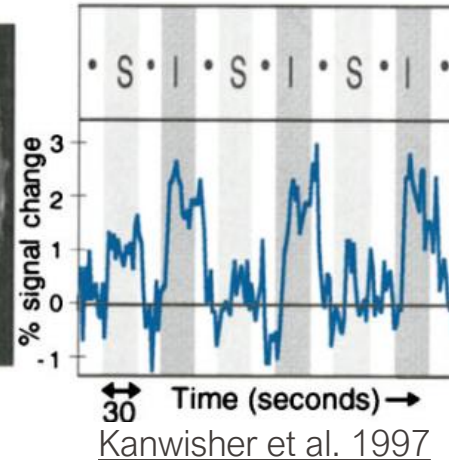
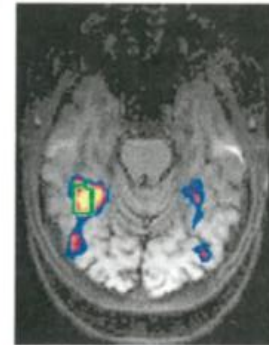
# Neurons in cortex are topographically organized



3a. Faces > Objects

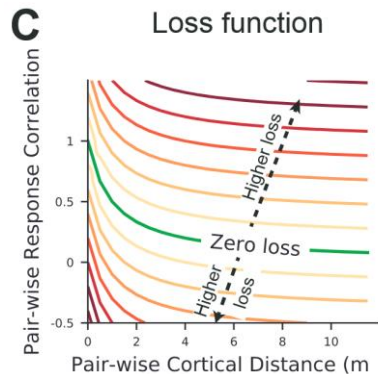
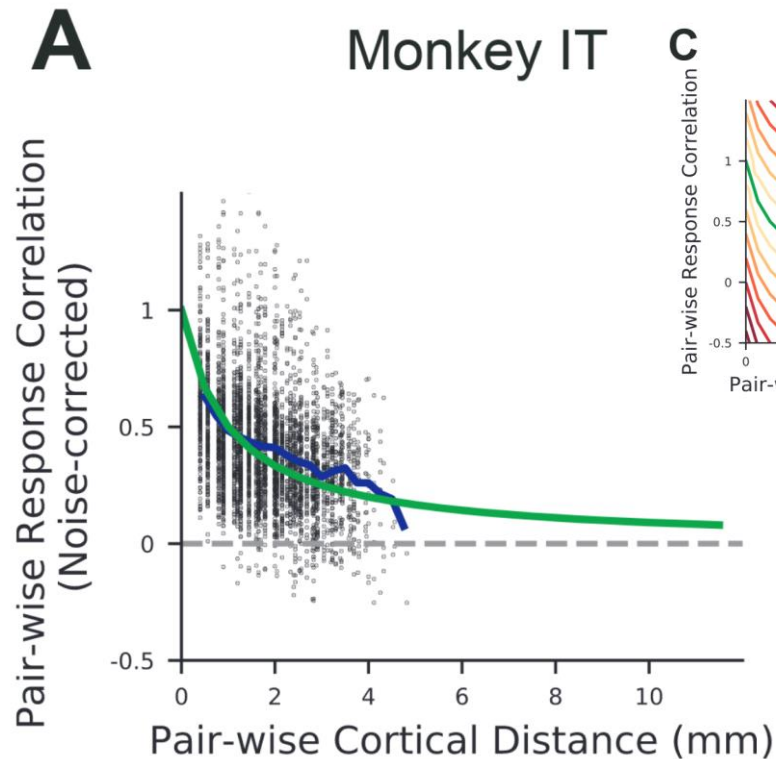


3b. Intact Faces > Scrambled Faces

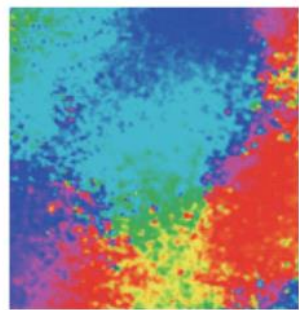


# Modeling spatial smoothness with a topographic loss

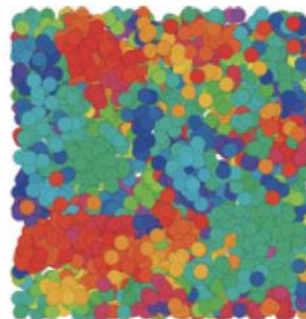
- A spatial loss term leads to brain-like clusters along the visual ventral stream (V1 to IT)



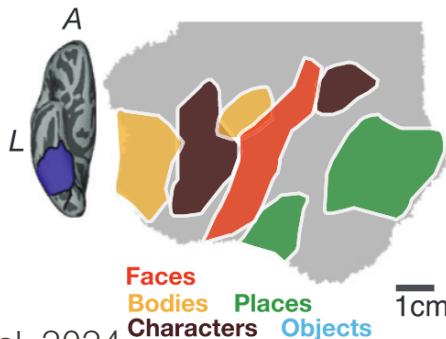
Macaque V1

200 $\mu$ m

TDANN

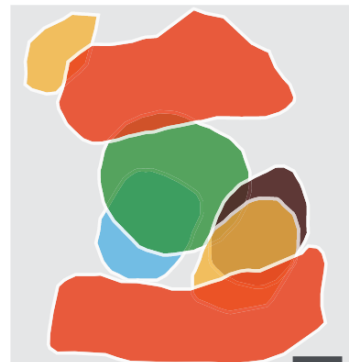
**F**

Human VTC



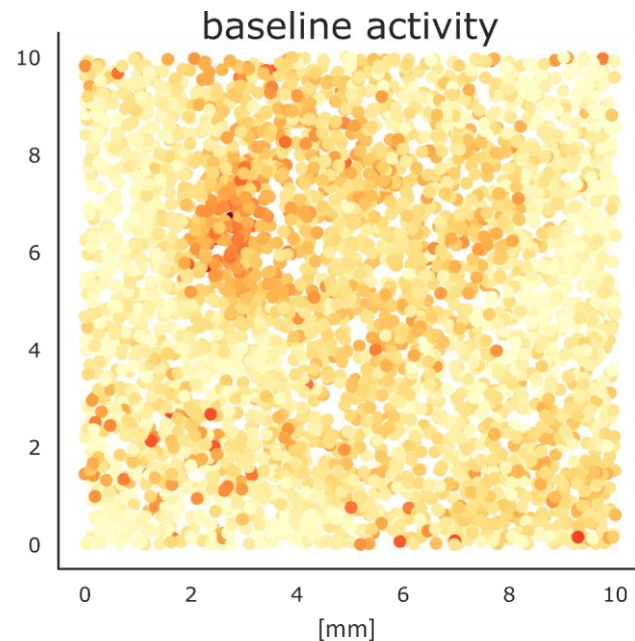
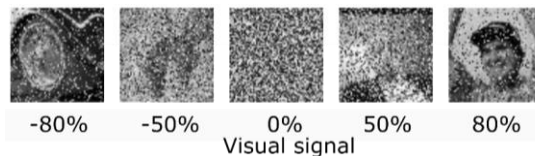
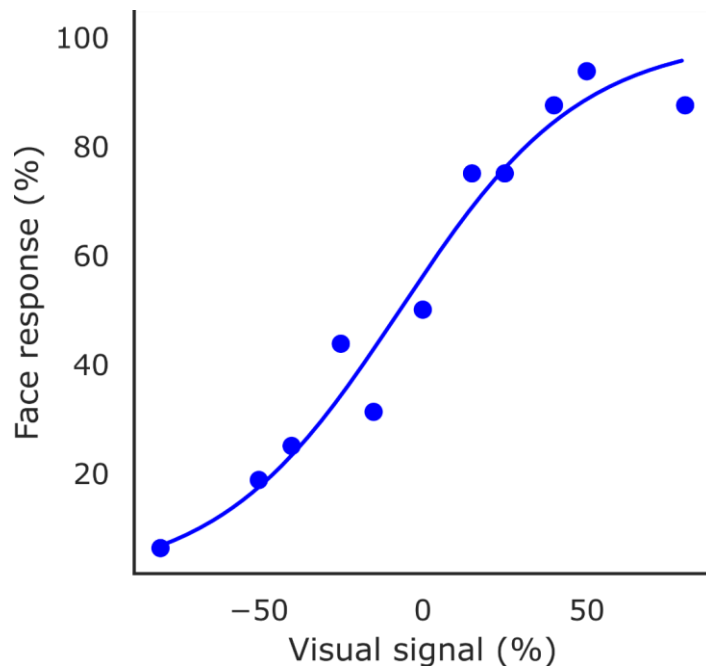
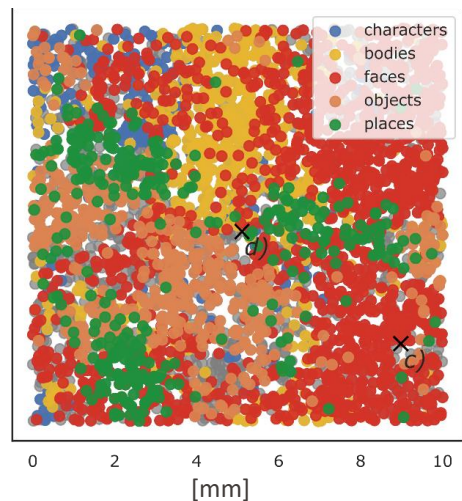
1cm

TDANN

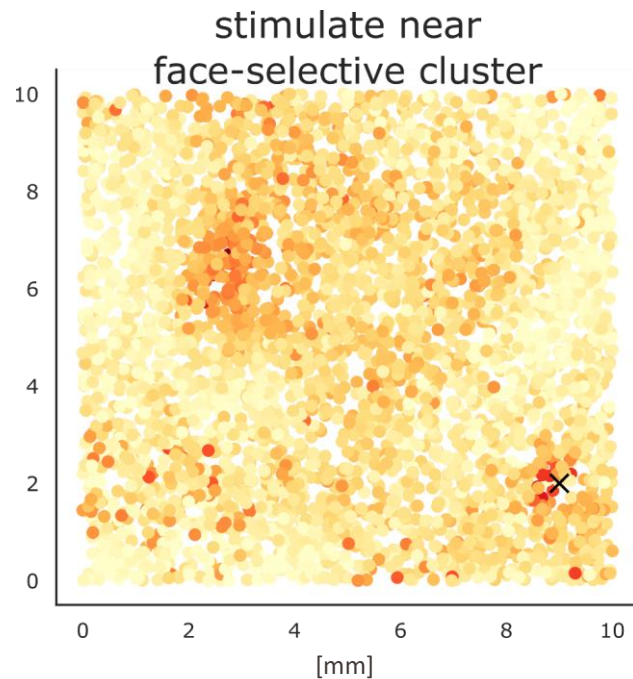
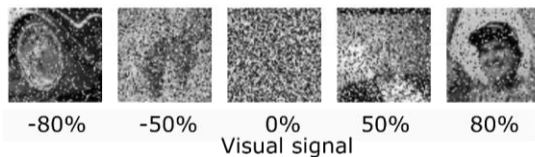
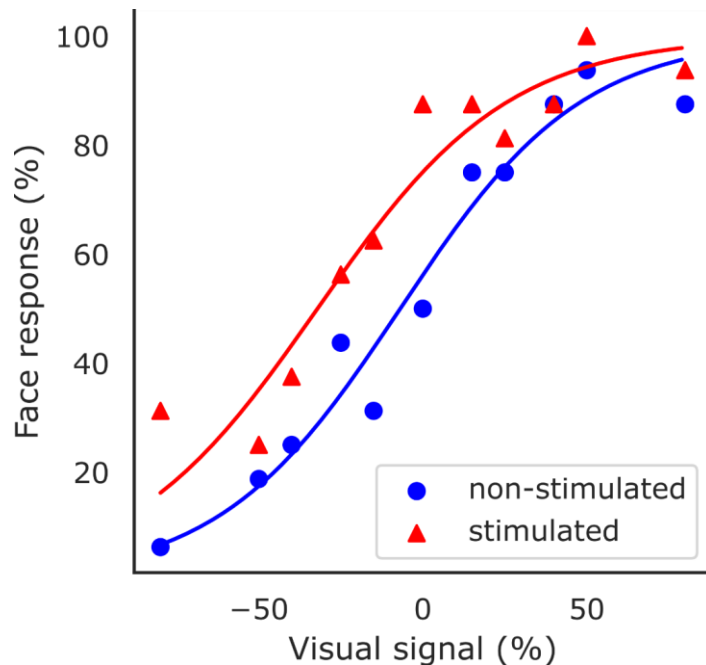
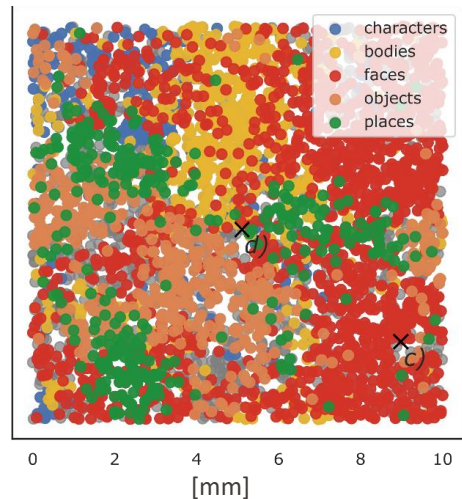


1cm

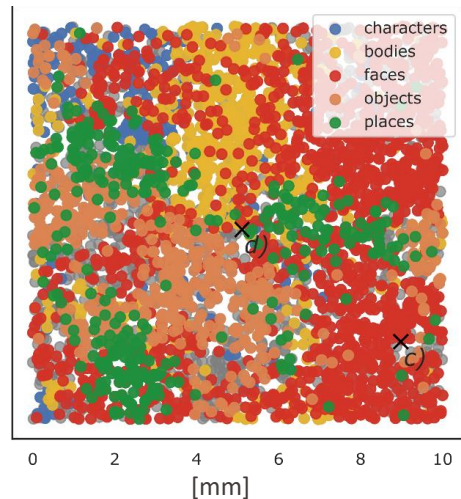
# EPFL Topographic models enable the modeling of causal interventions, e.g. micro-stimulation



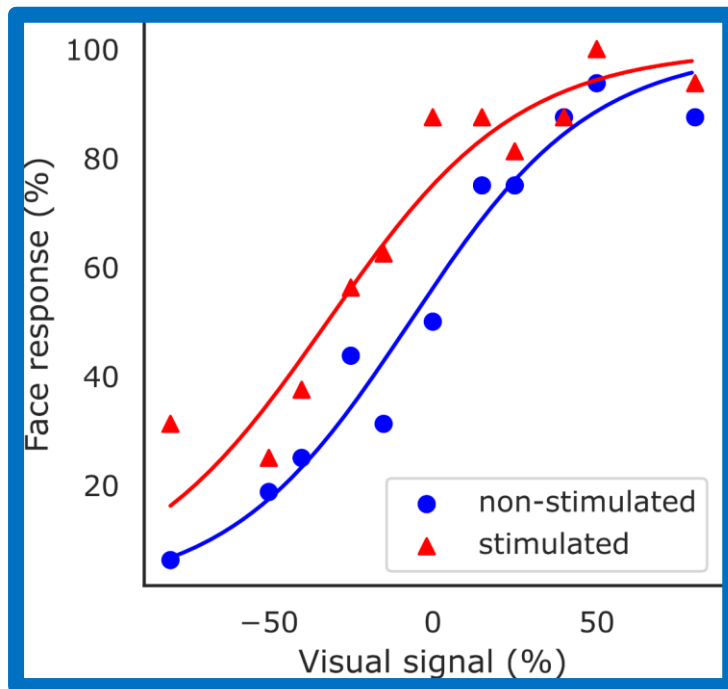
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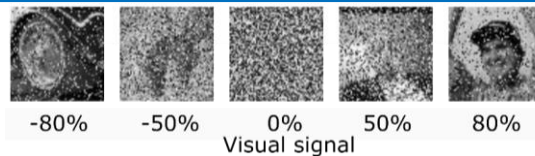
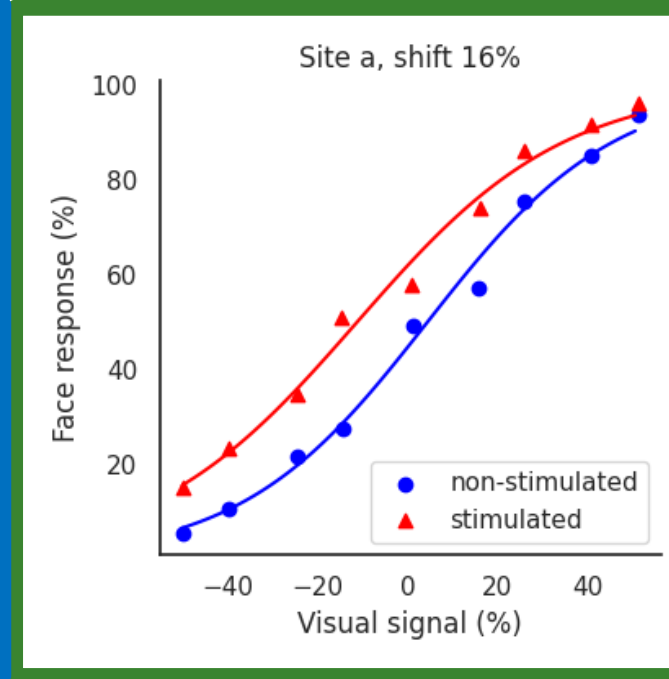
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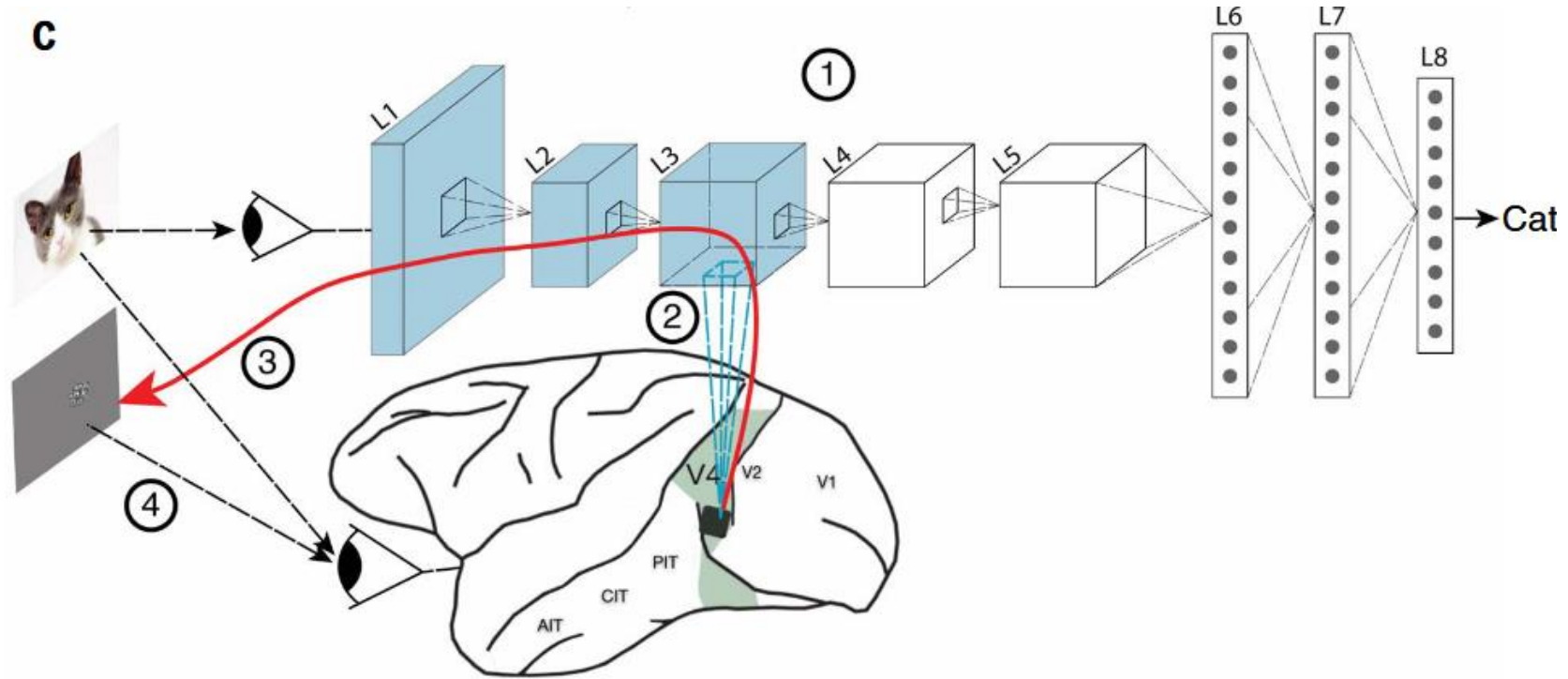
MODEL PREDICTION



BIOLOGICAL DATA (Afraz et al. 2006)

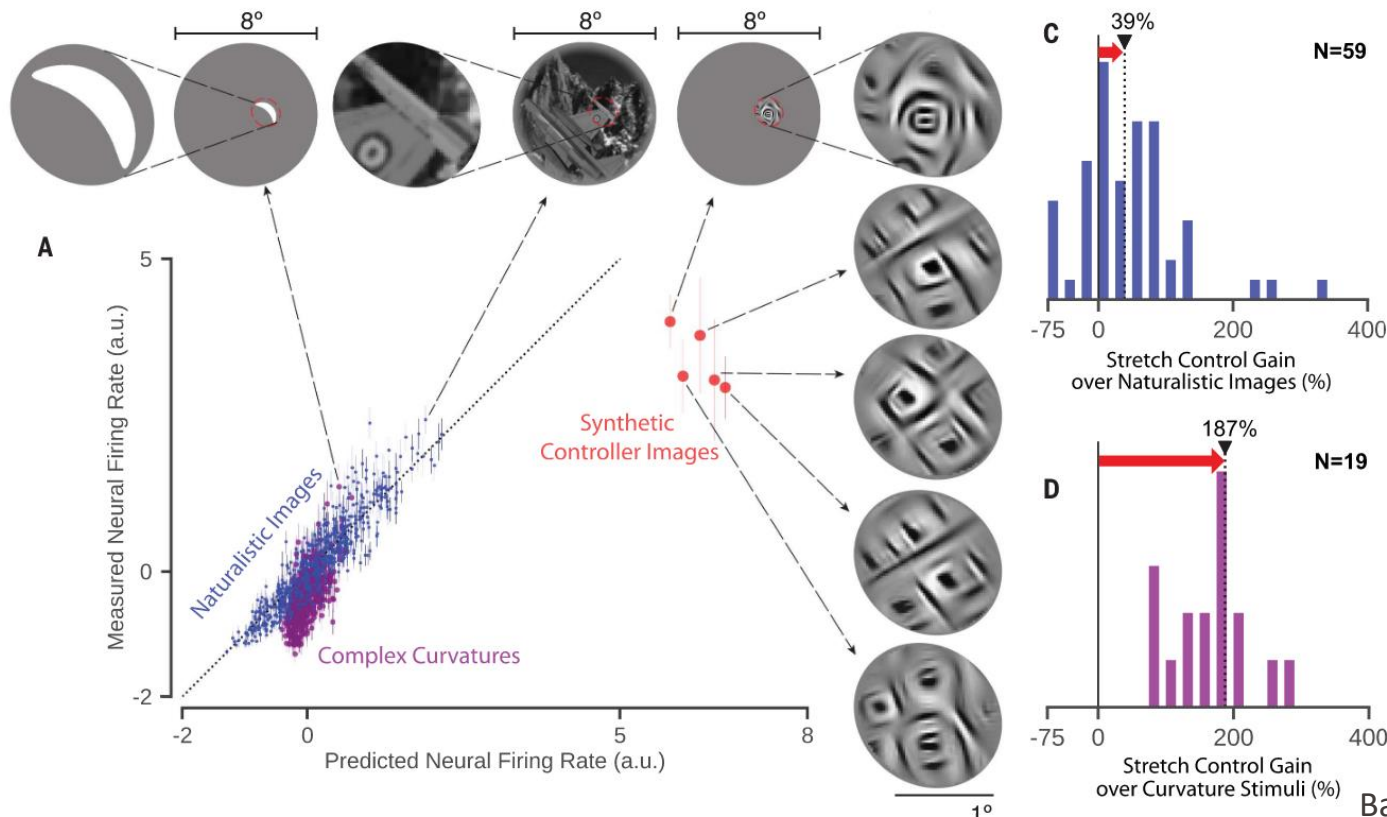


# Synthesis of stimuli for neural population control



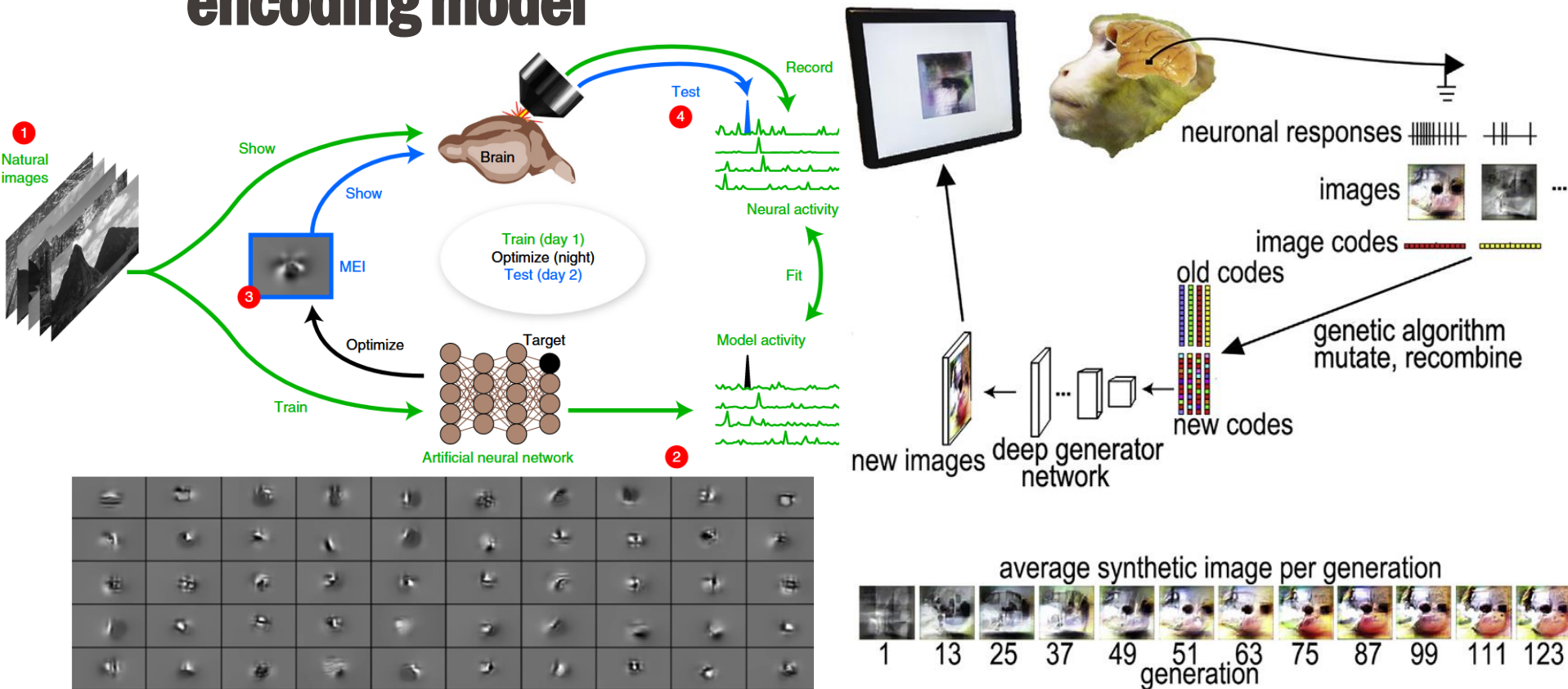
- Idea: model is fully differentiable, so we can set a desired target neural activity and update pixels in a way that they elicit the target state (according to model predictions)

# Model-guided synthesis non-invasively controls neural activity



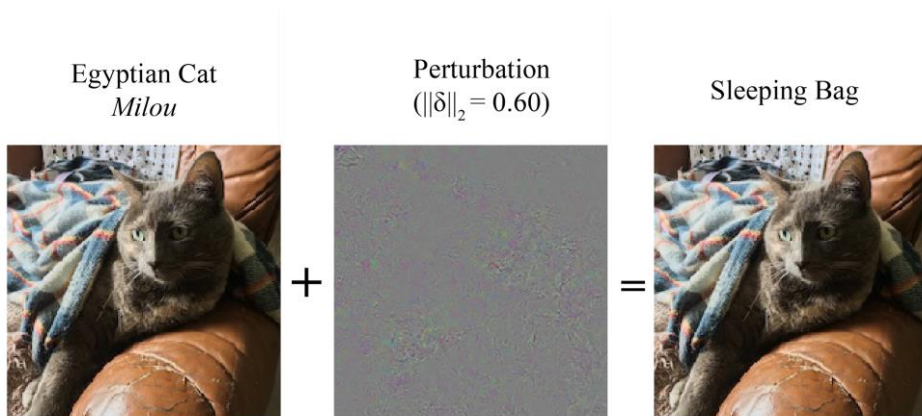
- This procedure works!
- We can generate stimuli that drive neural activity beyond the typical range
- This is a non-invasive control procedure

# Generating “exciting” stimuli without a pre-trained encoding model



# Adversarial attacks in computer vision

- Models are fooled by small, imperceptible perturbations (white box adversarial attacks)
- Protection technique: train on adversarial images “adversarial training” (very costly)



Graffiti

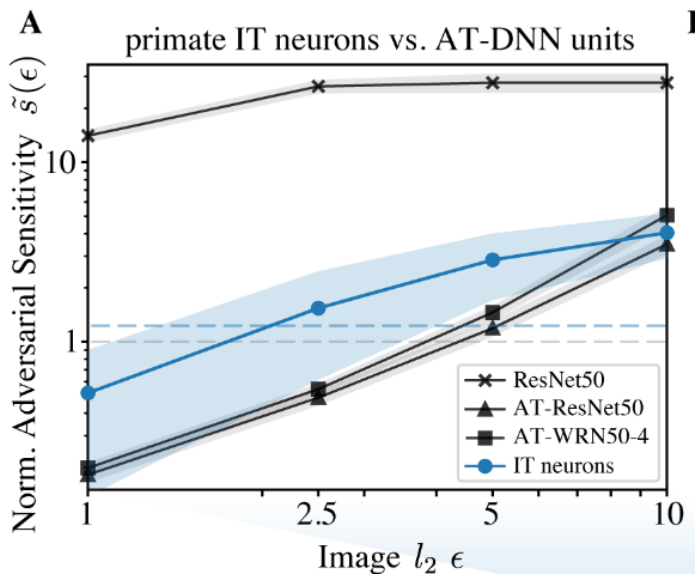


Image from *Dapello\*, Marques\*, et al. (NeurIPS 2021)*

*Szegedy et al. (ICLR 2014)*  
*Eykholt\*, Evtimov\*, et al. (CVPR 2018)*

# Adversarial attacks on the brain

- Prevalent view: only computational models are susceptible to adversarial attacks
- But: can synthesize images that also fool IT neurons



**A** preferred images



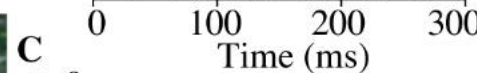
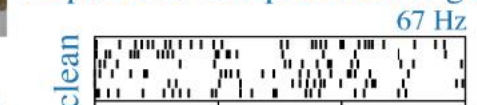
non-preferred images



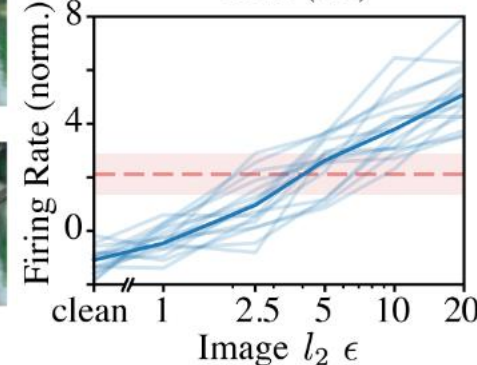
**B** response to preferred imgs.



response to non-preferred imgs.

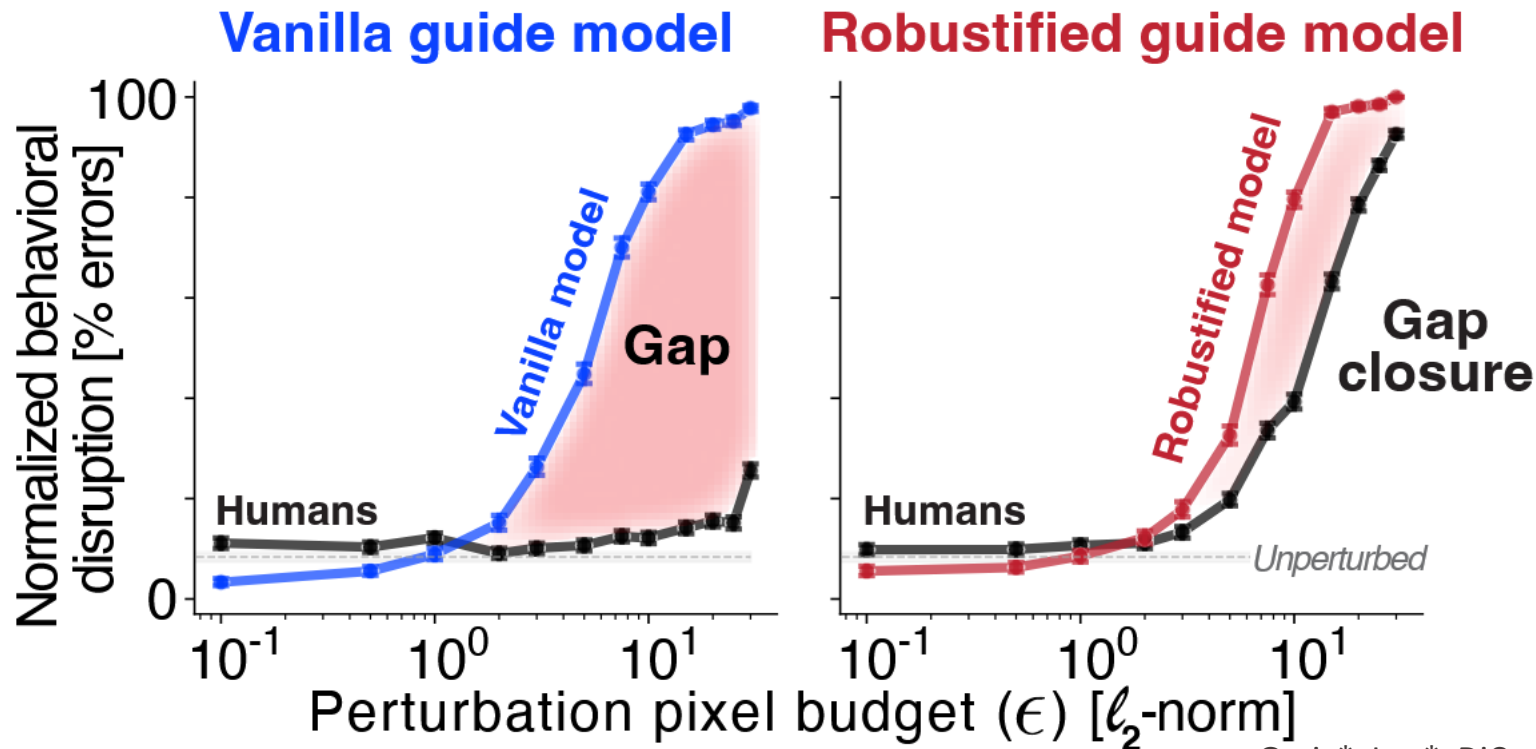


**C**



# Adversarial attacks on behavior

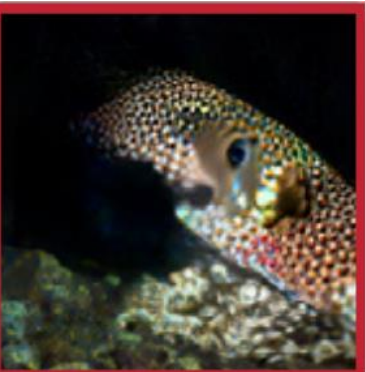
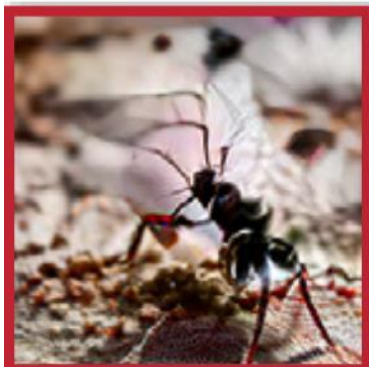
- Using a robustified model (trained with adversarial attacks), can change images in a way that change the decision of humans



# Adversarial attacks on behavior

start  
images

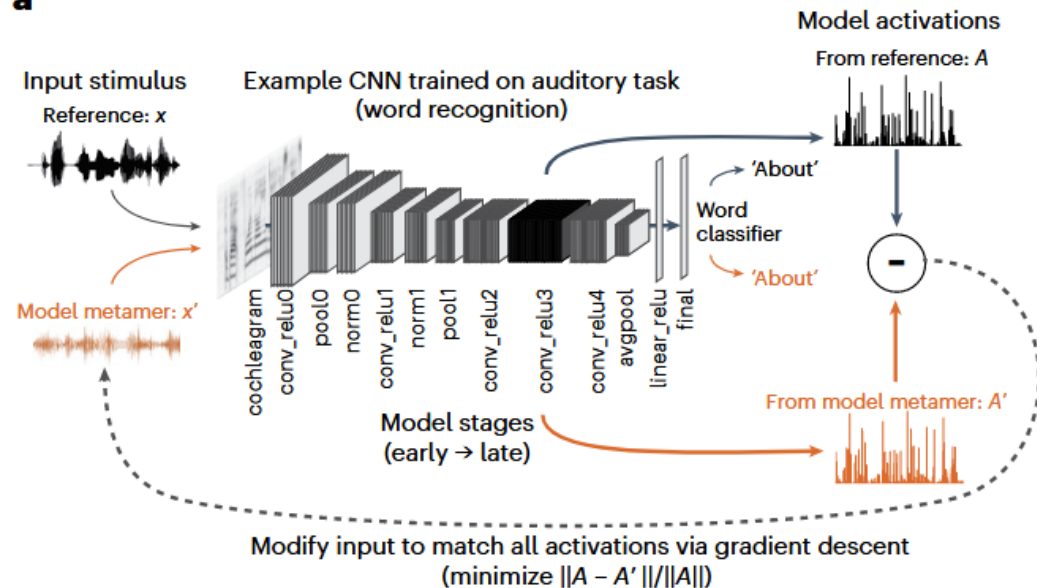
Example target categories  
'insect' 'primate' 'fish'



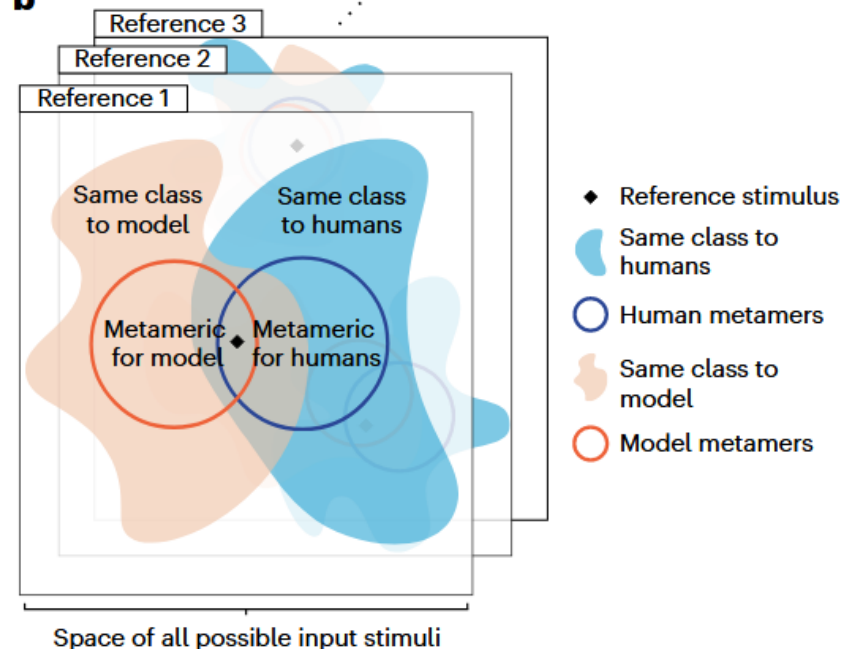
# Metamers

- Model metamers: “stimuli whose activations within a model stage are matched to those of a natural stimulus”

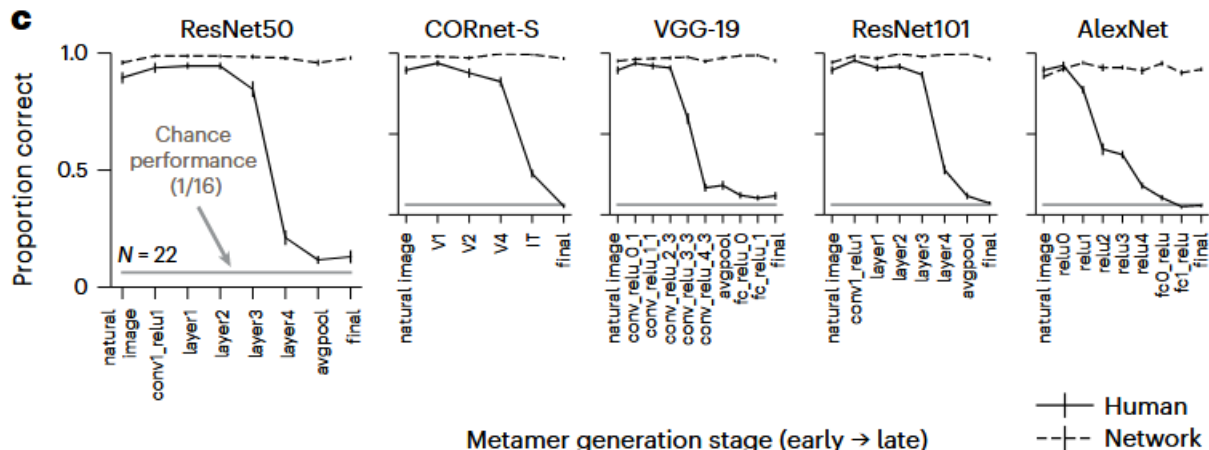
a



b



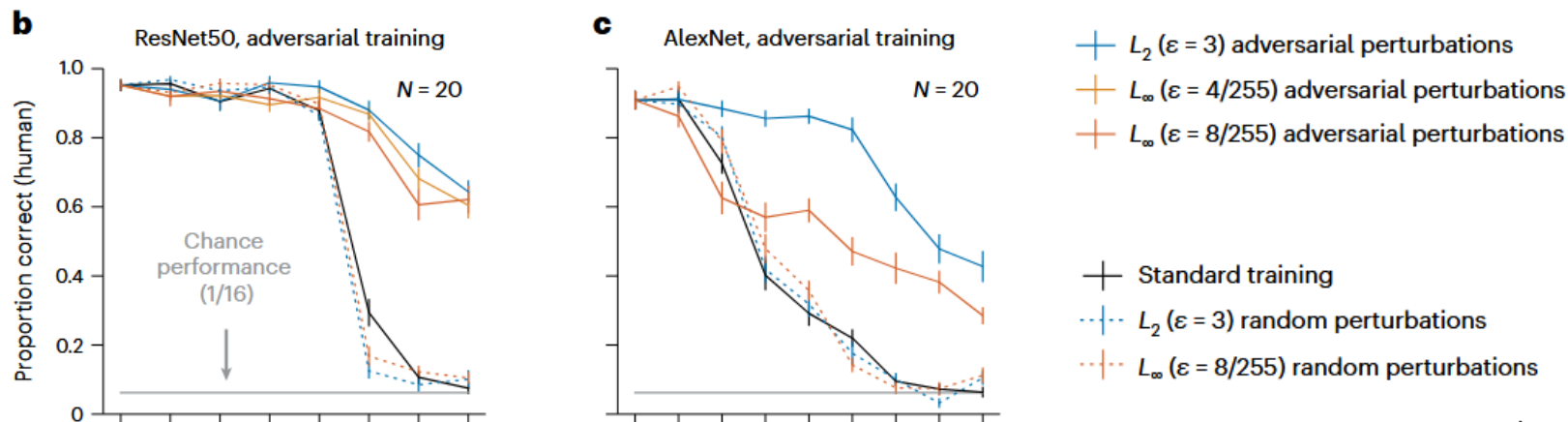
# Metamers of standard models are not recognizable by humans



Example metamers (visual networks)



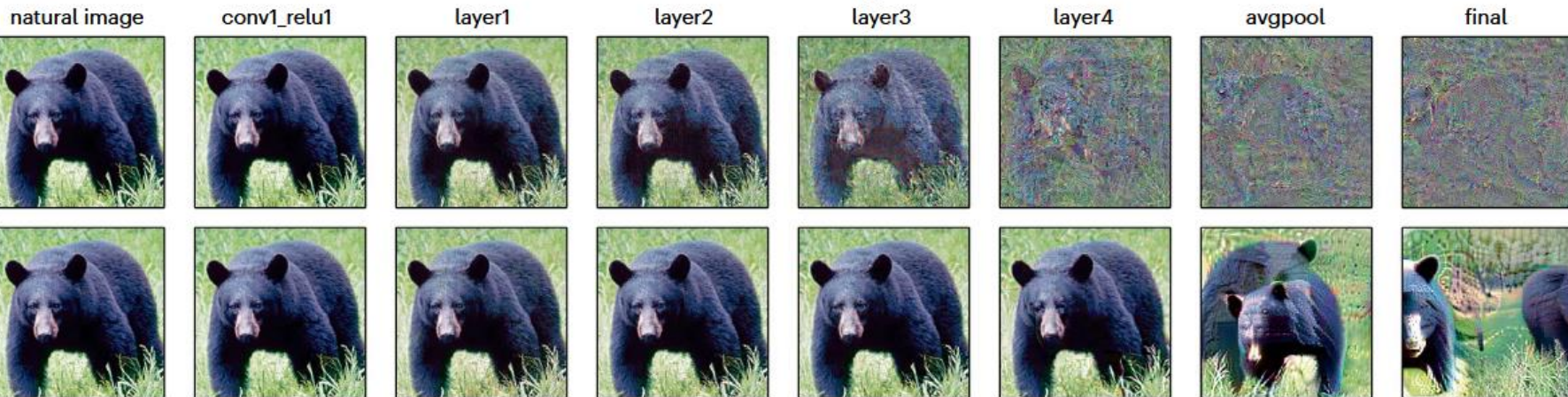
# EPFL Adversarial training makes metamers human-recognizable



Feather et al. 2023

**d**

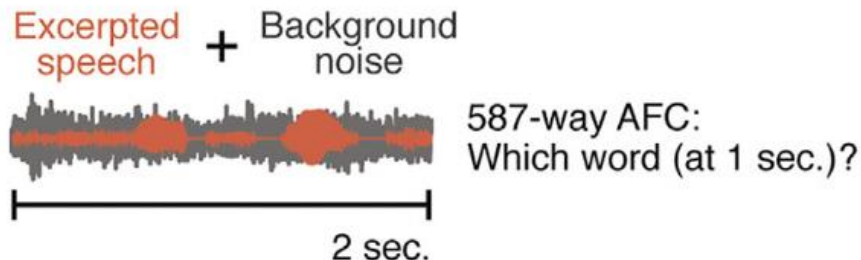
Example metamers (ResNet50,  $L_2$  perturbations)



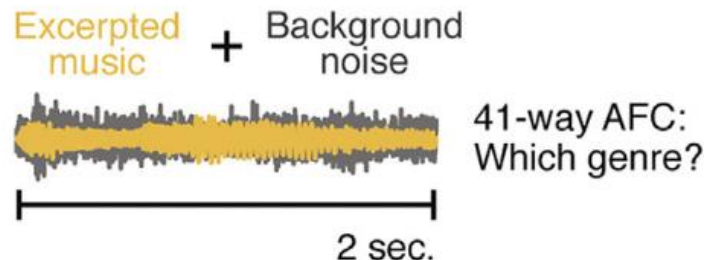
# EPFL Models of auditory processing

- Jointly optimize CNN for word + genre recognition tasks

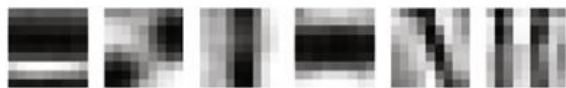
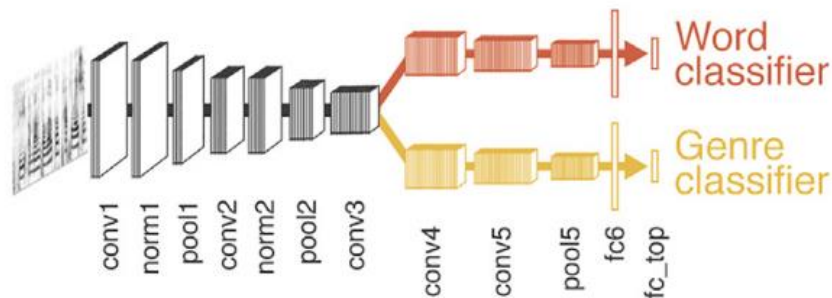
## A Word recognition task



## Musical genre task

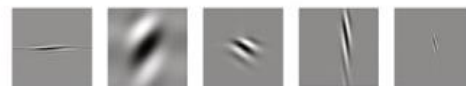
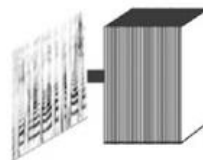


## E Best-performing deep neural network



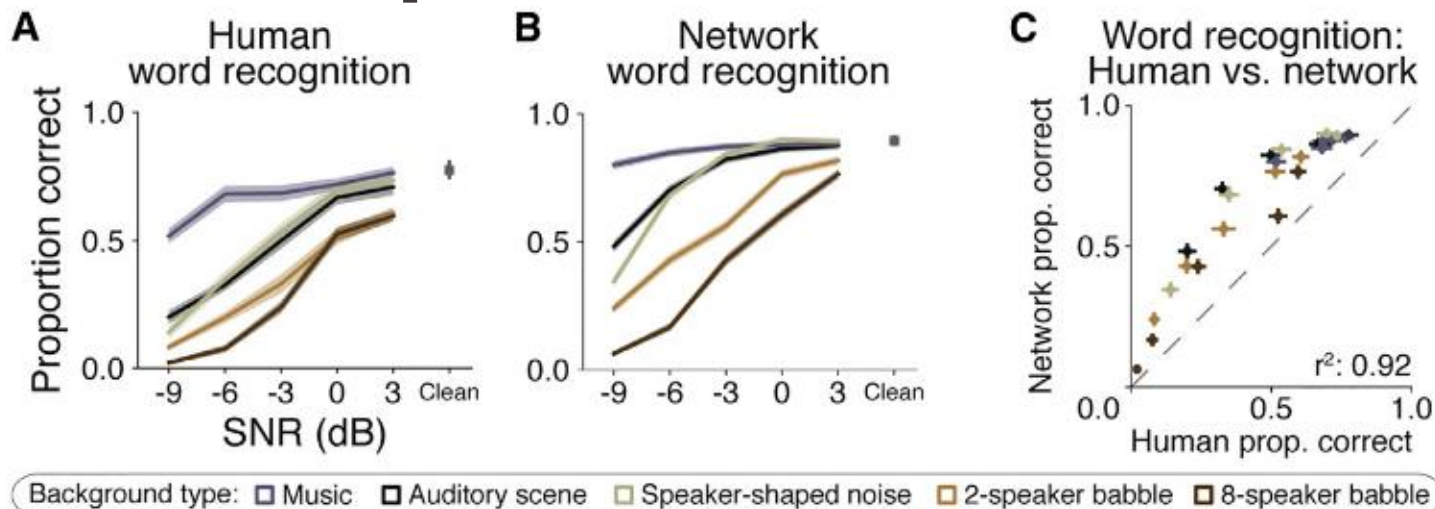
Example first-layer filters

## F Baseline model: Spectrotemporal filter bank

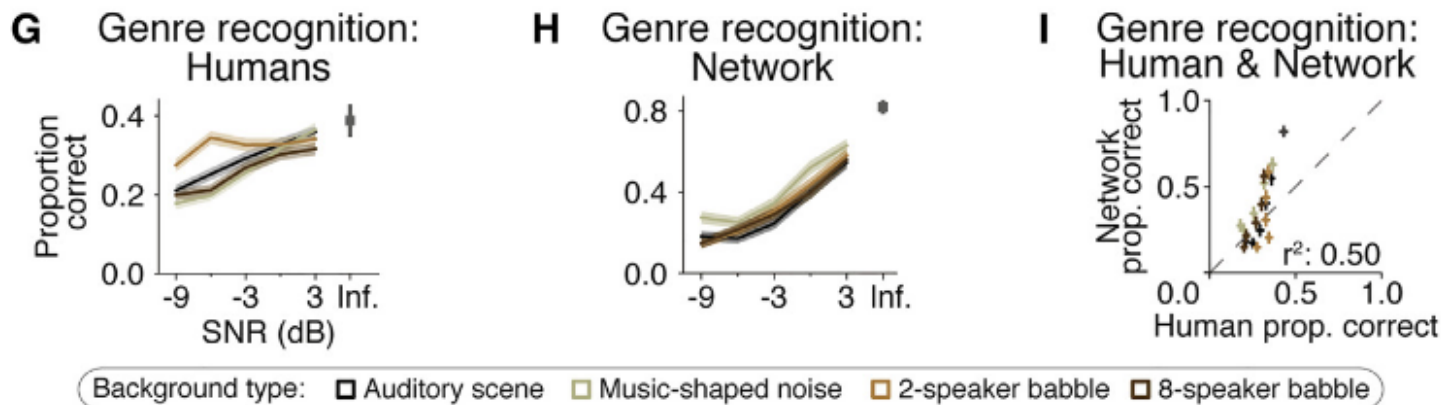


Example spectrotemporal filters

# Task-optimized model exhibits human-like behavior



- Model closely predicts human performance patterns, especially for word recognition tasks



- Less behaviorally-aligned for genre recognition

# Task-optimized audio model predicts fMRI responses

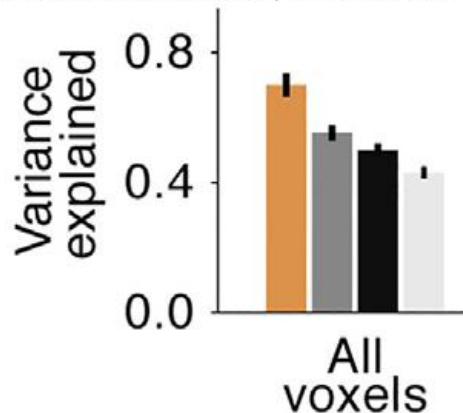
- The task-optimized audio model predicts brain activity in auditory cortex better than baseline models

■ **Trained network** (selected architecture, trained filters)

■ **Spectrotemporal model**

■ **Random-filter network** (selected architecture, untrained filters)

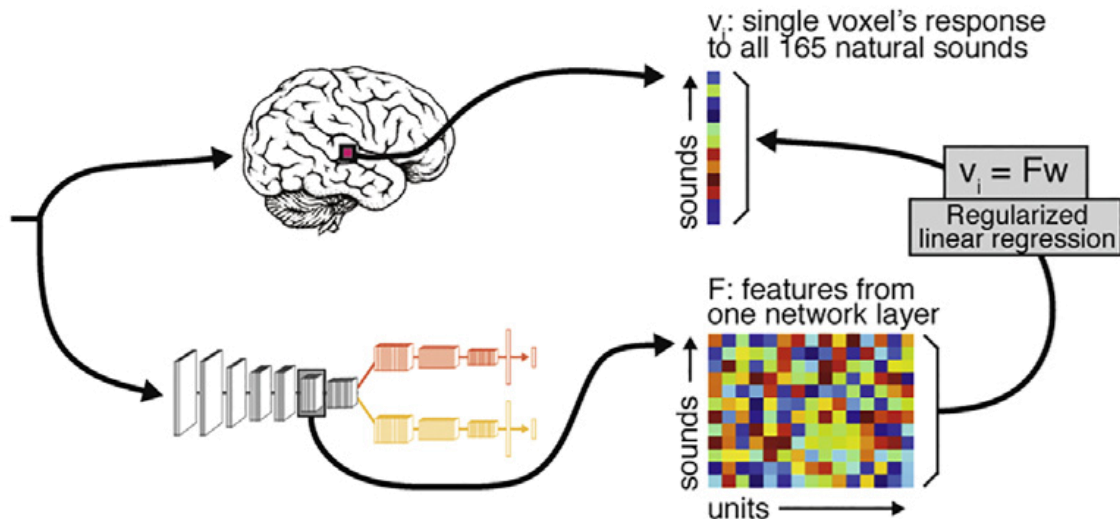
■ **Random-filter network** (unselected architectures, untrained filters)



**A**

165 everyday sounds:

person screaming  
velcro  
whistling  
frying pan sizzling  
alarm clock  
cat purring  
guitar riff  
... etc. ...



Region of interest

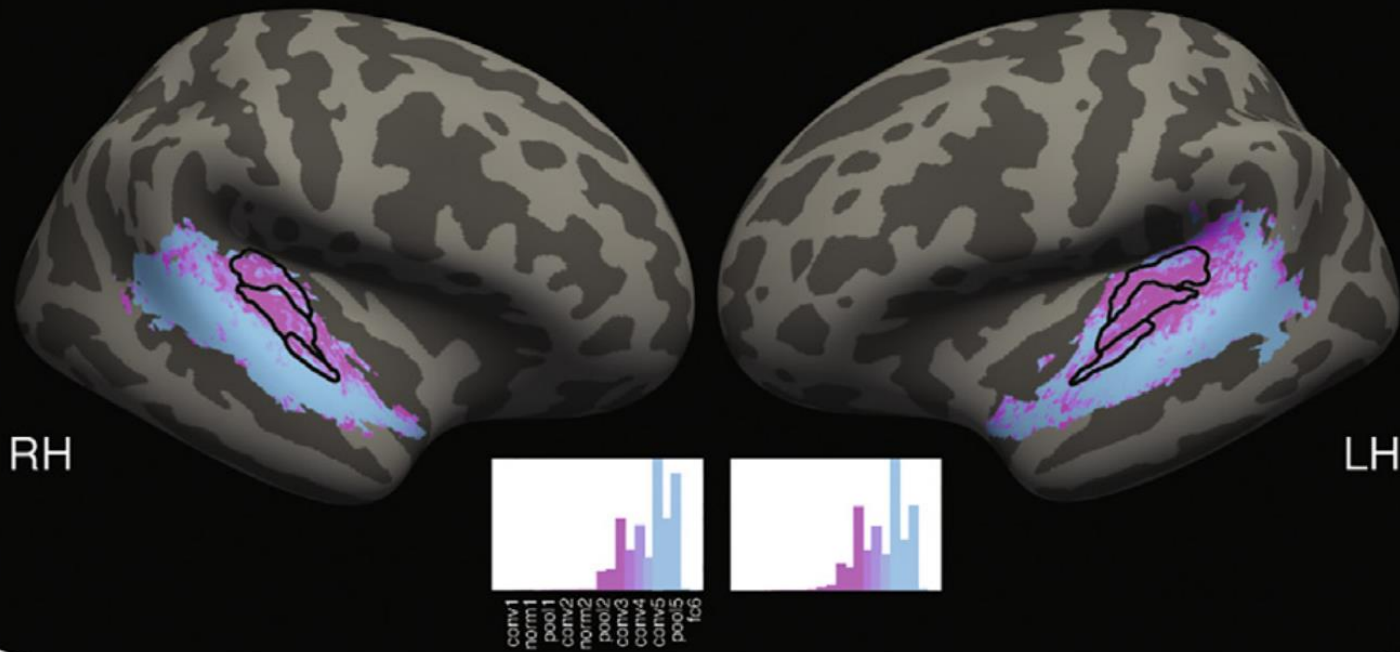


# Model Predicts Hierarchical Organization in Human Auditory Cortex

**B**

## Best-predicting network layer for each voxel

Layer:    ■ conv3 or lower    ■ conv4    ■ conv5 or higher



- Black outline: sub-divisions of primary auditory cortex
- Primary auditory cortex best explained by earlier layers
- Later layers best explain non-primary areas

# Take-home messages

- Unsupervised training yields brain-like representations
- Including a spatial loss term leads to topographic models that reproduce the spatio-functional organization in the brain. These models can predict the behavioral effects of neural interventions
- Encoding models of brain function allow for the synthesis of images to control neural activity. Can create images akin to adversarial attacks
- Yet, models often view things as identical that appear very different to humans (metamers)
- Very similar ideas from vision work for models of auditory processing